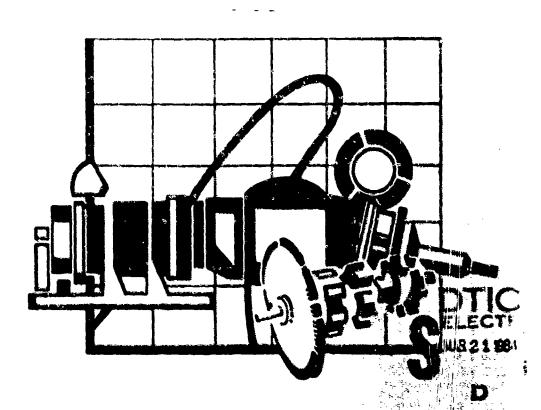


ORGANIC RANKINE CYCLE SILENT POWER PLANT, 1.5 KW, 28 VDC

FOR

U. S. ARMY MOBILITY & & D CENTER

FORT BELVOIR, VIRGINIA



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ENGINEERING REPORT

ORGANIC RANKINE CYCLE
SILENT POWER PLANT, 1.5 KWe, 28v DC
FOR
ELECTROTECHNOLOGY DEPARTMENT
ELECTROMECHANICAL DIVISION
U. S. ARMY MOBILITY R & D CENTER
FORT BELVOIR, VIRGINIA 22060

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SECTION I ACKNOWLEDGEMENT

I. ACKNOWLEDGEMENT

Many individuals and groups have worked enthusiastically toward developing this Organic Bankine Cycle Silent Power Plant. While all individuals cannot be identified, following is a list of those who formed a nucleus on this extension program. Louis Suit, Boland Christen, Gary Peach, Timothy Bland, William Smith, and many other support individuals and groups.

SECTION II
TABLE OF CONTENTS

TABLE OF CONTENTS

Sect	ion	Page No
1	ACKNOWLEDGEMENT	1
11	TABLE OF CONTENTS	2
Ш	INTRODUCTION	3
	Set 1 Development Summary and Conclusions	
١٧	SUMMARY	10
v	DESCRIPTION	15
VI	COMPONENT DEVELOPMENT	. 24
	Constant Frequency Motor Noise Gearbox Noise Noise Frequencies Identification from Test Data Improvements in Gear Noise Reduction CRU Noise Offset Gearbox CRU (Combined Rotating Unit) Valves Pitot Pump Boost Pump Start Approach	24 24 28 29 34 35 44 56 56
ve	SYSTEM DEVELOPMENT	69
	Steady State Operation	69
VIII	IMPROVEMENTS	98
	Output Power and Efficiency	98 98 108
łX	CALIBRATION REQUIREMENTS SUMMARY	110

SECTION III

Under USAMERDC Contract DAAK02-72-C-0472, Sundstrand has been developing an organic Rankine cycle, 1.5 KWe, 28 VDC, portable silent power plant. A summary of the specification requirements is presented in Table III-A. To date, two (2) development sets have been delivered to USAMERDC, Ft. Belvoir, Va. The development of Set 1 is described in Sundstrand Report ATR 1182, 6-24-74; the following report describes the development of Set 2. The following introductory paragraphs summarize the results of Set I development and the basis for improvements planned for Set 2.

Table III-A Specification Requirements

- 1.5 KW, 28 VDC, Closed Rankine Cycle
- · Portable, skid mounted
- Silent at 100 meters
- Capable of withstanding extremely hard usage encountered in military field application simulated by free fall flat and end drop (18 and 12 inches respectively), vibration, railroad impact at 10 mph and in transit road test
- Locally or remote station startup within 10 minutes by an integral stored energy source and a manual or external energy source
- 65°F to +125°F ambient temperature, any humidity
- Minimum 3000 hours operating life
- Minimum 7.5% Set efficiency at 1.5 KW output
- Maximum 150 lb, dry weight
- Maximum 8 cubic foot volume
- Multi-fuel operation
- Inclined operation, 31⁹ from horizontal
- Minimum 95% Set reliability
- Start and operate at 1.5 KW in rain and wind (12 in/hr and 40 mph respectively).
- 4% voltage regulation, 2 seconds recovery time, 2% voltage stability, 26-34 volts adjustment, 3% voltage ripple, adjustable current limit, 30% voltage dip and rise, overload of 110% and overspeed of 125%
- Design for human performance and engineering
- Major component characteristics
 - Boiler-Burner Heatup to operating temperature and pressure in three minutes, equipped with automatic controls, electrical power supplied from alternators
 - Working Fluid Circulating System: Includes condenser, preheater if required, feed pump. No significant working fluid loss for two years or 10,000 hours of operation.
 - Throttle Valve Used to control vapor flow
 - · Governor Required to sense and control engine speed to essentially a constant level
 - Condenser: Must be compact, light weight, vapor to air using blowerfs).
 - Regenerator: Utilize if overall cycle efficiency can be improved.
 - Lubrication System: Must be suitable for include parts and hermetically scaled for engine
 - Alternator To be brushless and have a static excitation system
 - Fuel System: Include light(,on source, integral fuel pump capable of pumping through a 25 feet line with a six feet static suction head, lines, filter and positive shutoff.
 - · Battery and charger
 - Controls for pressure, speed, temperature and power conditioning

SET 1 DEVELOPMENT SUMMARY AND CONCLUSIONS

The program consisted of:

- Packaged development Set and breadboard controls
- Limited component and subsystem testing
- No breadboard system testing

in terms of development effort, some of the critical subsystems of Set No. 1 resulted in:

- Air/Fuel System developed more than 100 hours of operation
- Turbine development 2900 hours of bearing testing
- Breadboard control system demonstrated/operational

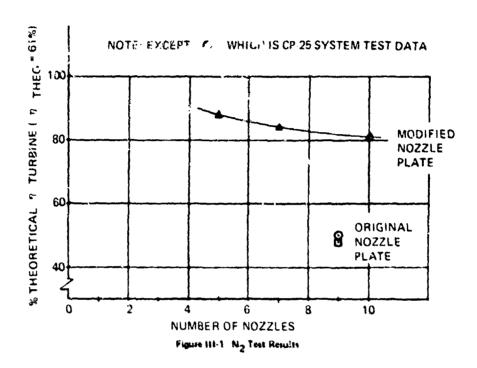
A significant amount of set testing resulted in:

- 69 hot tests
- 15 hours of hot testing on the turboalternator, regenerator and condenser
- 20 hours of hot testing on the heater and burner
- 75 hours of operation on all accessories

There were several nuisance types of problems encountered throughout the Set 1 development period, some of these were resolved. There were major problems which were identified, including potential solutions. These prevented complete self-contained operation and full power output from being demonstrated and are listed below.

- Low turbine performance
- Apparent low turbine existing temperature
- Structural flexibility of the turbine balance assembly and hotsell
- Pitut pump performance

It was demonstrated that low turbine performance was primarily due to too large spacing of the turbine norzhe and correcting this would enable at least 84% of predisted turbine power to be achieved. Figure 111.1 shows the data for the Set No. 1 noszle plate and a test noszle plate with close-spaced (touching edge-to edge) noszles (Figure 111.2). With the exception of the one point taken from set data, all data are for bests conducted on a test rig using high pressure nitrogen is drive the turbine. It can be seen that the original noszle plate produced 48% of the predicted turbine efficiency. By reducing the noszle spacing the turbine views a continuous rather than internettent driving gas stream as the wheel rotates past each noszle. The result is a substantial increase in rurbine efficiency.



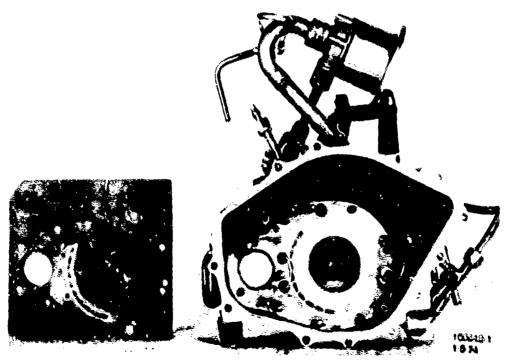


Figure III-2 Task and East 1 Grazale Plates

The resultant projected system performance with the modified nozzle plate is shown in Figure III 3 to be 1.1 KW net output at an average 8% active nozzles which corresponds to the maximum flow that the system can support. The burner has overfire capability but of unknown extent. However, at 10 active nozzles (the limit of the present design), 1.47 KW net output power can be produced. Whether this can be achieved is dependent upon the extent of the overfire capability, the heat exchangers, the achievable reduction in parasitic power and the turbine pump characteristics.

Another problem was low turbine exhaust temperature. It was hypothesized that quenching of the turbine exhaust was occurring due to fluid migrating from the pitot pump area. Shifting the pitripump from the turbine wheel end of the assembly would permit any leakage to fall to the hotwer. The Set No. 1 and revised configurations are shown in Figure iII. 4.

Also, the flexibility of the turbine balance assembly and hotwell, or the CRU (combined rotating unit), has resulted in rubbing at the turbine wheel hub and pitot pump housing regions. These have all been light and non-damaging in nature but nonetheless result in undesirable noise, vibration and power consumption. Improved balancing, an increase in the shaft diameter and noncantilevered mounting of the turbine balance assembly in the hotwell have shown by test to be an improvement.

SET 2 IMPROVEMENT PLAN

The following improvements were considered advantageous to incorporate into Set No. 2 which comprises the basis of this report.

CRU redesign	Includes a new, close spaced nozzle plate, stiffening of the forward and aft hotwell housings, larger diameter shaft, shifting she pitot pump aft and moving the bending critical speeds above the 55,000 rpm operating speed.
Buost pump	Improving the capability of the boost pump to operate with a boiling fluid will improve operation margin.
Noise reduction	Several sources of emitted noise include the CRU (nousing resonance) and accessories such as condenser fan and gearbox, should be identified and reduced to acceptable level.
Control valves ·	Sticking of the control valves appears to be related to clearances, contamination and coll size, reliability of operation should be improved through correction.
Pockaged controller	The present (Sat No. 1) breadboard controller should be packaged into a configuration

consistent with mounting in the unit

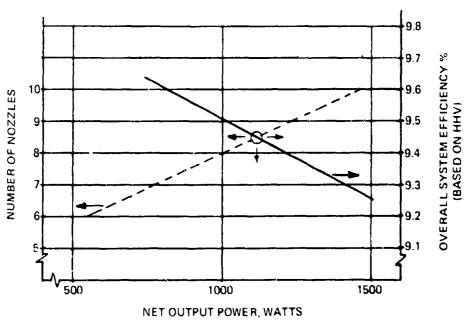
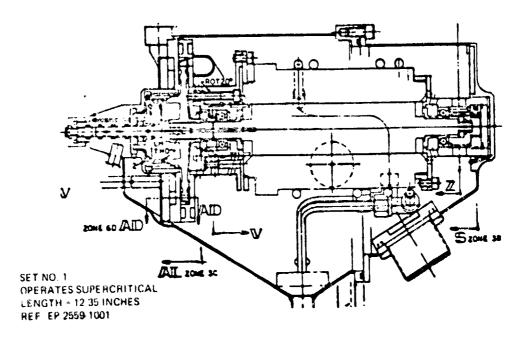


Figure III-3 Projected System Performance



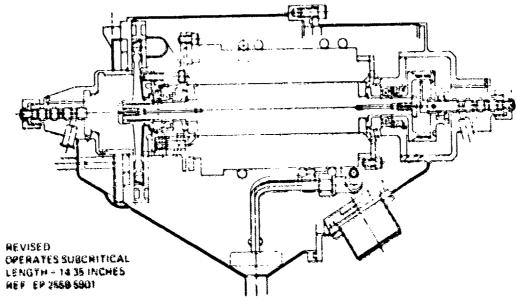


Figure III-4 Set No. 1 and Revised CRU Configurations

Parasitic power reduction

Startup

Accessory power is considerably higher than desired and those areas where reduction is readily achievable should be investigated.

The Set No. 1 startup method involves retaining pressure in the accumulator from the shutdown and/or pressurizing as required to the desired level by the handpump. Both start pressure and start flow valves must be extremely leak tight. Other approaches, which may be simpler, e.g., start pump assisted starts, should also be investigated.

SECTION IV

IV SUMMARY

This report is a summary of the development of a 1.5 KWe, 28 VDC organic Rankine cycle power plant. It specifically describes the degree of progress made between Set 1 and Set 2. Set 1 was described in Report ATR 1182 and delivered to USAMERDC at Ft. Belvoir in the first quarter of 1974. Set 2 is described in this report and was delivered in the first quarter of 1975.

Figure IV-1 is a photo of Set 2. Table IV-A summarizes its characteristics and Table IV-B is a summary of the 1.5 KW organic Rankine cycle modification benefit matrix. The Set is a low volume (~2' × 2' × 2'), low weight (212 lb), multifuel (demonstrated on MIL-T-5161 primary fuel and W-F-800 alternate fuel) machine that has had several improvements incorporated. Relative to Table IV-B these include all of Item 1.0, 2.0, 4.0, 5.0, 6.0, 7.0 and part of 8.0.

Except for battery start, the set is self-sufficient. Output power has been as high as 477 watts. The set has not achieved design power (1.5 KW) primarily due to heat losses and shunts within the machine, slightly lower than design turbine efficiency and lower pitot pump efficiency. Of these, the pitot pump predominates. A small effect in low output power is due to the regenerator effectiveness and heater efficiency being lower on Set 2 than that demonstrated on Set 1.

The lower pitot pump efficiency is attributed to changes in the pump housing and the pitot probe between Set 1 and Set 2. When designing the pump for Set 2, an approach thought to not functionally impact the pump performance was followed to reduce fabrication cost. This has proved to be detrimental.

Set 2 is a functional power plant. Its deficient output power needs correction through improvement in the performance of the components contributing most to the problem. Table IV-C summarizes these improvements and the resulting output power using actual test data presented in this report as a basis.

Other areas in need of further development include automatic startup and noise level, neither of which meet specification requirements although improvements have been made in both areas in progressing from Set 1 to Set 2.

Other areas where improvements have been made include control valves that are free from sticking, a significant reduction in parasitic power (approximately 76 watts), and an improved boost pump.

Set 2 is a significantly improved functional unit compared to Set 1 and represents a considerable step towards evolving a portable multifuel, 1.5 KWe, 28 VDC, silent power plant.



Figure IV-1 Set No. 2 on Test Stand

Table IV-A Power Plant Characteristics

Production Prototype Package

Weight:

212 lb.

Volume:

7.7 cu. ft.

Performance:

Tests show potential for thermal efficiency of 10.4-13.9%

Durability:

In accord with specification

Operation:

1500 hrs. on CRU bearings 60 hrs. on accessories each Set 20 hrs. on hermetic system each Set Demonstrated multi-fuel capability Packaged controls demonstrated

Other:

Reduced gearbox noise (Set 2 lower than Set 1)

Reduced start complexity (Set 2 less complex than Set 1)

Reduced parasitic power (Set 2 lower than Set 1)

Table IV-8 1.5 KW Organic Rankine Cycle Modification - Benefit Matrix

MODIFICATION	COST	ST	WEIGHT	F	EFFIC	EFFICIENCY	RELIABILITY	HLITY	NOISE	35	
	Buduce	Anduce Increase	Reduce	Increase	Reduce	Reduce tocrease	Reduce	Increase	Reduce	Reduce Increase	Comments
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B. B. Section Properties and Contraction of the section	*		×			×		×			
1.f. etterteftump	16		×					×			
1.6. Termprepare Standy Corner	×		×			×		×			
P.G. Char three stranger etectors to ground constand spring stranger was	•	¥				×		*			
2.0 Godfivenburtogic	×		*			×		×			
4 S ABC Start Pump		¥		×	*		-	×		×	
6,0 Bedenign fusette Plene					۔ ــ	×					
6.10 Relietinte Picot Rump						×		×	×		
P.O. Recension Bosom Fump				×	,T			×			
6.0 Sections Accommeny (driverie)	¥						×		×		
DE And Fund of five Circuit		×		×	····	×		×			
CO. C.	¥ 		×		~	×		×			
11.S Add Aucumenal Camping		¥		*					×		
13.10 Auchauge Variable Spend Charact	·					×					
68.6 Reserven Meaner	4		×			×		×			
B. B. D. M. Benger. Magerene eren	¥		×	, .		×		×			
S.S.O. Mortonispo Tearthon						×					

Table IV-C Improvements

Improvements

Turbine: Increase lap ratio to raise turbine efficiency from

mid-50's to design point of 62%; requires no R&D.

Pitot Pump: Increase efficiency by reducing drag, recirculation

Iceses and housing effects through examination of

variables experimentally.

Regenerator: Lower effectiveness of Set 2 compared to Set 1

hypothesized due to sidewall leakage; design to

eliminate.

Heater: Lower η of Set 2 compared to Set 1 hypothesized

due to manufacturing QC; improve and go to fin-tube

derign.

Performance Expections

Output Power

At $\eta t = .58$.35 - .65 KW (met)
Plus reduced heat loss .38 - .68
Plus design regenerator effectiveness .60 - .85
Flus design pitot pump efficiency 1.1 - 1.43
Plus design heater efficiency 1.2 - 1.57

Plus design heater efficiency 1.2–1.57
Plus increased fuel flow >1.5 KW (net)
System thermal efficiency (based on HHV) 10.4–13.9%

Output power improvement would also be achieved in a variety of other ways including reduced parasities, improved rectifier efficiency and increased generator performance.

SECTION V

V. DESCRIPTION

A general description is presented, followed by a description of how Set No. 2 differs from Set No. 1.

The Set uses a supercritical closed loop organic Rankine cycle with CP-25 as the working fluid. Figure V-1 shows a working fluid flow schemat : and corr sponding TS diagram.

The general overall mechanical arrangement of the Set is shown in Figure V-2 with some of the details in Figure V-3. All of the components are mounted to a common support plate which is shock mounted from the main support structure. The condenser regenerator, battery/instrument compartment, and condenser fan are located in the upper portion of the unit. The rest of the components are located in the lower section.

Protection of the unit from rough handling is provided by a tubular frame surrounding the unit. For further protection, including environmental conditions, covering and weather cap are provided. The weather cap is aluminum with a layer of sound absorption material bonded to the inner side. The upper cover is a fiberglass shroud while the lower covering consists of five panels of an aluminum/rubber honeycomb composite. These materials provide protection as well as reduce emitted noise.

Easy access to all interface points is provided though the Set is tightly packaged. Brith the burner exhaust and cooling air flow merge in the unit and exit through the opening between the upper portion of the shroud and the weather cap. When operating in an enclosure where warm air exhaust is to be used as space heat, the burner exhaust can be separately ducted away.

Access to the miserator interface points is provided through the hinged front door. This area exposes the hand grank, hand pump, manual valves, fuel reservoir and fuel filter. The battery door is also hinged for access and battery replacement. Electrical and fuel hook-up points are accessible externally since these connectors protrude this up recesses in the side panels. For maintenance purposes, all panels may be removed using a screeniliver.

A system schematic of Set No. 1 is shown in Figure V-4, and Figure V-5 illustrates the schematic for Set No. 2 along with identification of instrumentation. Figure V-6 is a functional schematic of the working fluid portion of the system. It can be seen that for Set No. 2, the accumulators, a harir valve, the start pressure valve, a check valve, the hand pump and the air compressor solengic valve have been eliminated. Instead of a pressurized accumulator start, a start pump is used which reduces the start complexity considerably. Table V-A is a weight summary of Set 2.

The controller of Set 2 is slightly different to that of Set 1 due to the component changes and development improvements as the following list indicates:

Set 1 Set 2

Fixed Inverter Purchased

Start pressure valve Eliminated

Temperature ready circuit Eliminated

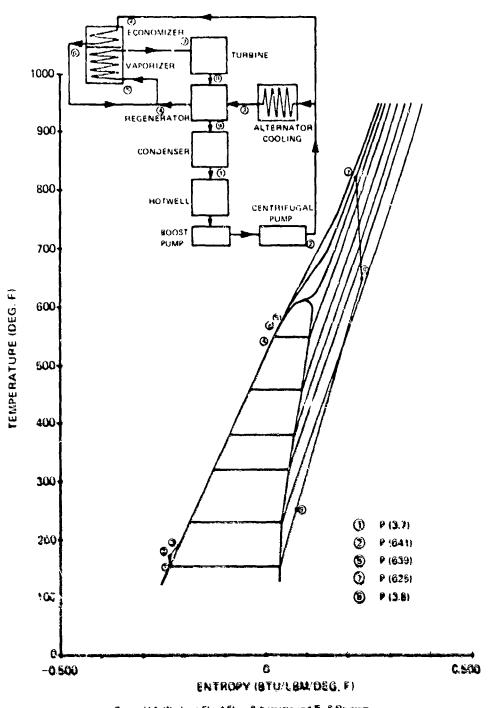


Figure V-1 Westing Fluid Flow Exhaustic and F=8 Dispus

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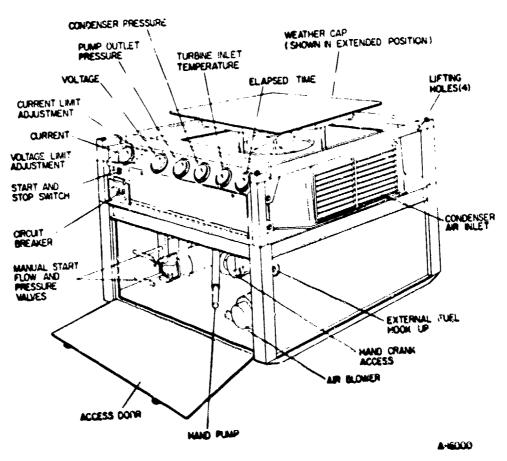
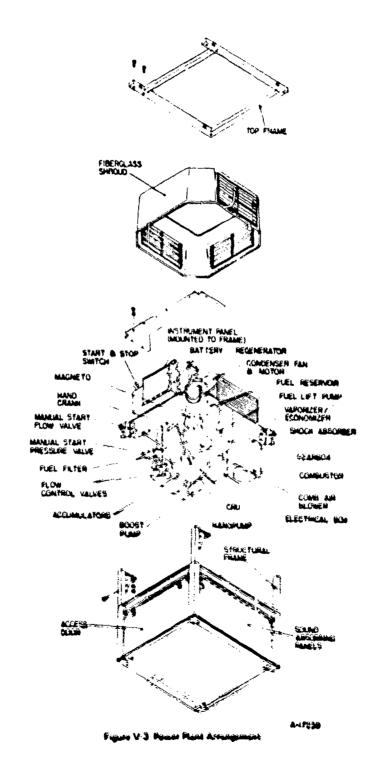


Figure V-2 Power Plant

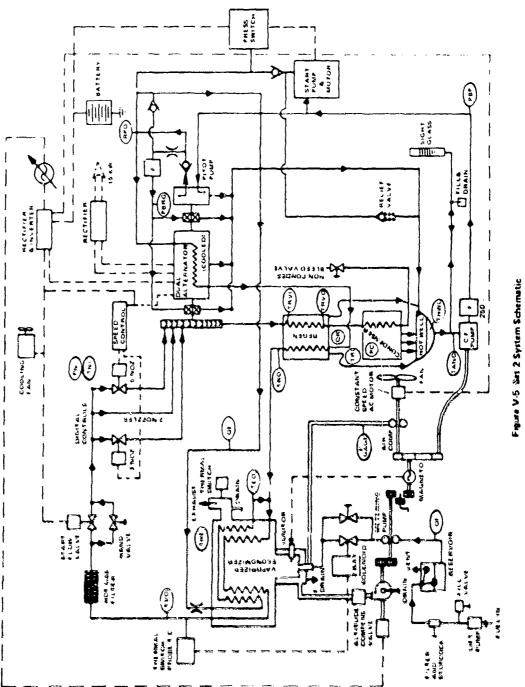


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Hure V-4 Set 1 System Sc



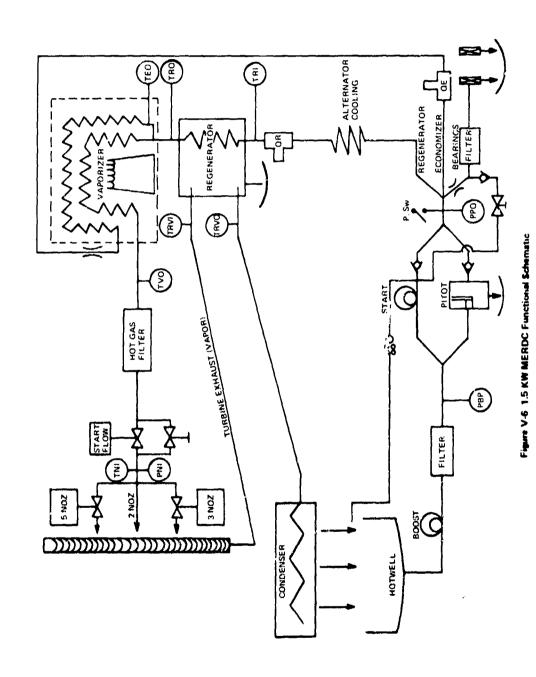


Table V-A Set 2 Weight Summary

Combustor Extension + Sight Tube	450 lb.
Hot Gas Filter	450 lb.
Shutoff & Control Solenoid Valve (S.B. 1.264 ea.)	795 lb.
Boost Pump (Gear Type)	312 lb.
Boost Pump Inlet & Outlet Plumbing + Fittings	700 lb.
Constant Frequency Fan	063 lb.
Condenser Overpressure Switch	512 lb.
Start Pump (.700), Motor (5.013), Coupling (3.000*)	713 lb.
	000 lb.
Battery and Gage Box	370 lb.
N-C Battery (9.637), Retainer (.250)	387 lb.
Constant Frequency Motor	575 lb.
Controller + Cover	188 lb.
Lift Pump, Fuel Sol. Valve, Bracket	000 lb.
	137 lb.
Magneto + Cable	000 lb.
Atomizing Air Compressor	938 lb.
Fuel Reservoir	563 lb.
Altitude Compensating Valve	375 lb.
Gages (.563 ea.)	380 fb.
Turbine-to-Regenerator Bellows	188 lb.
	2 50 lb.
Fuel Metering Pump, Coupling, Screws	300 lb.
Condenser Assy	375 lb.
Fiberglass Cover (6.938), Weather Cap (2.500)	138 lb.
Regenerator	750 lb.
Panels (4 Sides + Bottom)	750 lb.
	000 lb.
Accessory Gearbox (Lower)	00 lb.
	325 lb.
CRU (Noz. Plt. = 11.1, Aft Cover = 6.11, Bal. Assy. = 17.3	510 lb.
Frame, Shocks, Mount Plate	900 lb.
Miscellaneous*	/ 06 lb.
Total Dry Weight	300 lb.
Total Wet Weight (2.4 lb. CP-25*)	XXX lb.
 Estimates; all others are measured weights 	

11日で大門のは代の経験的は対象を選出しています。

Controller cooling fan

Eliminated

Solenoid air compressor valve

Eliminated

Accumulator underpressure

Eliminated

Eliminated

Start pump pressure switch

Eliminated

Start pump soft start circuit

The fixed inverter was purchased for Set 2 and mounted outside the controller, consequently, the cooling fan was eliminated due to lower controller heating. For the pump assisted start, the temperature ready, accumulator underpressure and the start pressure valve circuits were not necessary. The combustor was determined to operate satisfactorily at low fire without reduction in air compressor pressure, consequently, the solenoid valve was eliminated. A pressure switch was added to shut off the start pump after the pitot pump takes over. For startup, to prevent overriding the start pump magnetic drive, a soft start circuit was also added.

SECTION VI
COMPONENT DEVELOPMENT

VI. COMPONENT DEVELOPMENT

Development tests were performed on the constant frequency motor to reduce parasitic power, the noise output of the accessory components, the boost pump to improve cavitation sensitive characteristics, the pitot pump to develop a cheaper manufacturing process, the control valves to provide more reliable operation, and the CRU to develop a higher efficiency, more vibration free and less noise producing assembly.

Following is a discussion of each of these development items:

CONSTANT FREQUENCY MOTOR

The constant frequency circuit consists of motor, inverter, gearbox, cover, magneto, boost pump, air compressor and condenser fan. It was predicted to draw 210 watts and measured to be 360 watts. Without the cover, the power consumption was 346 watts, and the largest difference between this and predicted was due to the 1 phase motor being 43% efficient. A 3 phase motor and inverter were designed. The test data is shown in Figures VI-1 and VI-2. In the operating region, the motor runs at 65% efficiency for an input power requirement of 270 watts.

When compared to the 1 phase motor/inverter, a power savings of about 76 watts is achieved and a start relay and capacitor are eliminated.

NOISE

The noise level of Set No. 1 was excessive. This was largely due to the vibration of the turbine rotating assembly inducing resonances in the hotwell fore and aft shells in which it is mounted. A variety of tests were conducted (at MERDC) using Set No. 1 as a test bed to separate out the excessive from the non-excessive noise producing components so that an improvement could be made with Set No. 2.

Audible noise spectrum data was taken with the constant frequency motor and associated accessories operating and then with the turbine and variable frequency circuit running. This data is shown in Figure VI-3, the analysis of which is summarized below:

GEARBOX NOISE

CALCULATING FREQUENCIES:

- (1) All fundamental constant speed motor gear mesh frequencies are about 3507.7 Hz, and the sum of gear mesh frequencies are about 7015.4 Hz.
- (2) The magnetomotive force wave frequencies from the electric motor are 1556.5 Hz, 1696.5 Hz, and 1826.5 Hz.
- (3) Line frequency and its first harmonics are 65 Hz and 130 Hz.
- (4) Rotor unbalance frequency is 57.5 Hz.

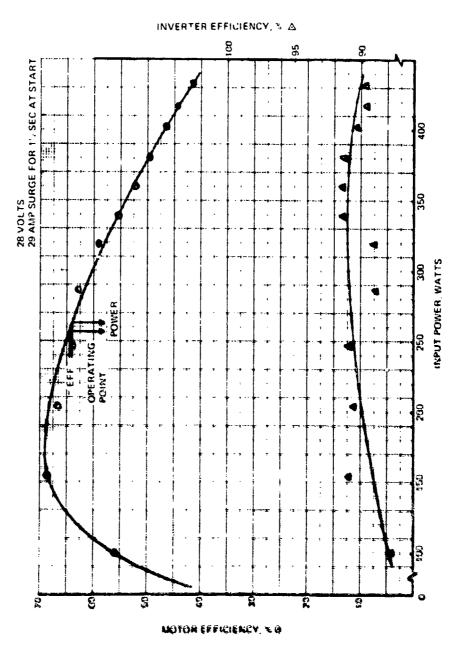
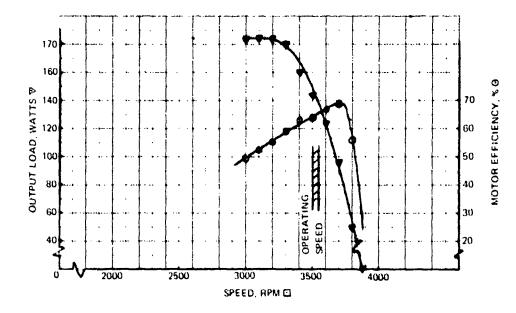
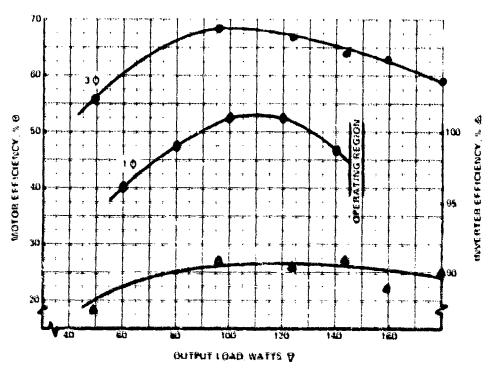


Figure VI-1 3 - Phase Motor





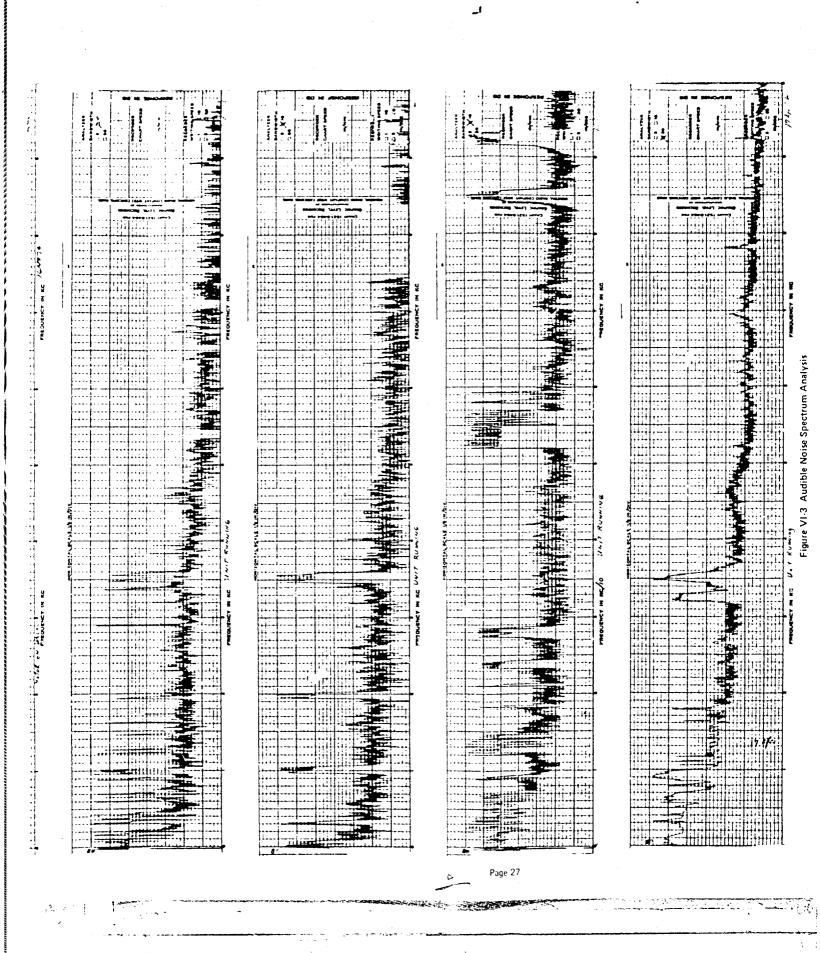
AUDIBLE ROISE SPECTRUP ARALTSIS LIBER SINDSTRAND OPERATO BANKINE CYPLE

Microphone located 18" from center of fuel pump aide condenser

Dart 1. Contant speed rotter 8 scensories, invarior dries Dart 2. Contant smeed rotter 8 occusionis, sanisc dries Dart 3. Unit number (string) Dart 4. Unit number (string) Dart 5. Unit number (string) Dart 8. Unit number, sanistan on 50 M bandeldo. (sarisc) Bandrel Redis Spectrum Analyzer, Sarisl Res. 276 & 1613.

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FIVE MOST PROMINENT FREQUENCIES FROM BEARINGS ARE LISTED BELOW:

- (5) Irregularity of a rolling element or the case = 23 Hz.
- (6) Fundamental rotational frequency of unbalance or eccentricity = 57.5 Hz.
- (7) Ball spin frequency = 110.4 Hz; 220.8 Hz.
- (8) hough spot on inner race frequency = 310.5 Hz.
- (9) Rough spot on outer race frequency = 207 Hz.

NOISE FREQUENCIES IDENTIFICATION FROM TEST DATA:

Five frequencies with high noise level in two sets of noise spectrum were identified and shown in the following table.

From these data, it is evident that the gear meshes caused the major noise in the motor gear system. A redesign of the gear train should substantially reduce the total gear motor noise.

Inverter Drive	Variac Drive	Cause Associated with Frequencies
3510 (80 d.B.)	3490 (76 d.B.)	(1) Gear Mesh (4 gears at the same frequency).
200 (72 d.홚.)	200 (69 d.B.)	(9) Rough Spot on Outer Race
310 (72 d.B.)	300 (76 d.8.)	(8) Rough Spot on Inner Race
600 (72 d.S.)	590 (68 d.B.)	(9) First Harmonics
160 (72 d.B.)	130 (66 d.B.)	(3) (4) (6) (7)

IMPROVEMENTS IN GEAR NOISE REDUCTION:

- (1) Helical types have the advantage of maintaining more than two teeth in contact during operation. Because of this, it is possible to get as much as 12 d.B.A. reduction in noise by using them instead of spur gears.
- (2) The finest possible pitch should be selected for the given load condition. This increases the amount of tooth overlap; the higher tooth overlap produces a smoother transfer of load, reducing dynamic oscillation of the gear mesh. This also will produce a higher mesh frequency; however, higher frequencies are easier to damp and easier to isolate than low frequencies.
- (3) The lowest possible pressure angle also can make gears tend to be quieter, because the transverse overlap ratio is higher.
- (4) For only one direction gear drive, recess-action gears can provide a further reduction in noise.
- (5) Gear noise at the mesh can be reduced by designing so that the total overlap ratio is an integral number of teeth. (Tests have shown that if the ratio is exactly 2.0, the smoothest transfer of load is obtained.)
- (6) Higher AGMA quality level (12 or better) gives smooth operation.
- (7) A non-integral gear ratio should be selected to prevent a tooth on the pinion from contracting periodically the same teeth on the mating gear.

Based upon these results, alternative offset (constant frequency) gearbox designs were made. Simultaneously, accelerometers were attached to selected locations on Set No. 1 and tested as follows:

Channel	Location	Test Condition
1	Aft CRU can, longitudinal	Constant f motor running
1	Right front frame, vertical	Constant f motor running
4	Aft CRU can, vertical	Constant f motor running
5	Mount plate, vertical	Constant f motor running
6	Offset gearbox, vertical	Constant f motor running
1	Aft CRU ean, longitudinal	Turbine running
5	Mounting plate, vertical	Turbine running
4	Aft CRU can, vertical	Turbine running

Figures VIII4, 5, 6 and 7 are representative plots of this data. Its analysis is summarized below:

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Figure VI-4 Channel No. 1 AFT CAN Longitudiral Constant Speed Motor Running

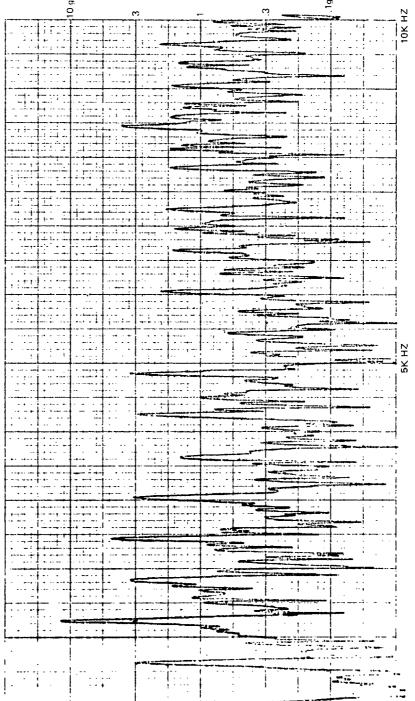
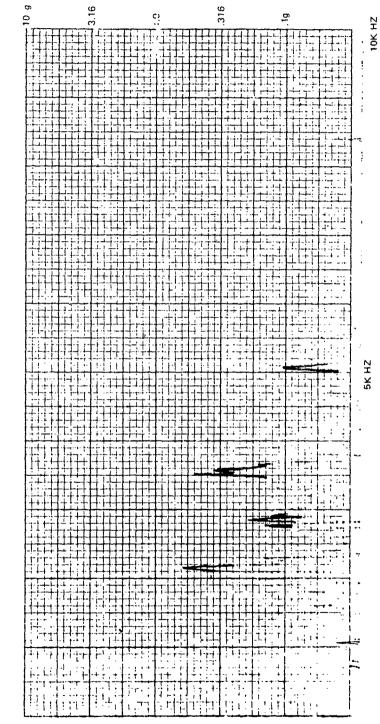


Figure VI-5 Channel No. 1 AFT CAN longitudinal Turbine Running



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e VI-6 Channel No. 5 Mounting Plate Vertical Constant Speed Motor Running

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Page 33

CPU NOISE

CALCULATING FREQUENCIES:

- (1) Roto, unbalance frequency = 625 Hz (37,500 RPM).
- (2) Element train passage or cage frequency = 260 Hz.
- (3) Ball spin and waviness frequency = 1247 Hz, 2494 Hz, 3741 Hz and 4988 Hz.
- (4) Rough spot on inner race frequency = 3287 Hz.
- (5) Rough spot on outer race frequency = 2340 Hz.
- (6) Variable contact compliance vibration frequency = 2340 Fiz, 4680 Hz, and 7020 Hz.
- (7) Flexural vibration of the outer ring caused by inner ring waviness of lower order = 1250 Hz, 1875 Hz, 2500 Hz, 3125 Hz, and 3750 Hz.

FREQUENCIES IDENTIFICATION:

Vibration data of Channel No. 5 was used to identify vibrator; mechanisms. The following table shows the result.

Frequency (Hz)	"G" Level	Cause Associated with Frequencies
620	7.4	(1)
1250	5.5	(3) (7)
1870	17.0	(7)
2450	2.5	(3) (7)
3100	1.5	(7)
3720	3.1	(3) (7)
4940	1.9	(3) (7)

DISCUSSION:

- A) From these data, it is evident that the rotor unbalance, ball waviness, and inner ring waviness of different orders caused the major vibration in this rotor-bearing system.
- B) The blade passing frequency is above the data cut-off (>10K Hz).
- C) Random type vibration is negligible.

IMPROVEMENTS:

- A) Better rotor balance (flexural rotor balance may be needed) gives smooth operation.
- 8) An increase in the number of balls results in a reduced vibration level generated from ring and balls waviness. For example, the change of nine balls to eleven balls could reduce the correlative vibration level by 10%.

C) Axial load and alignment of the bearing should be carefully designed and checked; the loose balls passing the unload zone or insufficient land height creates additional vibration.

It should be noted that this data was taken with the turbine operating at 37,500 RPM. Based upon these test results, the following changes were implemented to the CRU to reduce imbalance induced vibrations:

Type Nozzle	Forward Can	Aft Can	Bending Criticals
EP2559-1228	Stainless Steel	Aluminum .032 thick	32 Krpm, pump hsg.
Used on Set 1	.032 thick		48 Krpm, no pump
EP2559 1228A	Stainless Steel	Stainless Steel	65 Krpm, pump hsg.
Used on Set 2		.075 thick	both ends

It should be noted that the noise emitted from Set 1 is significantly greater than the specification. The major contributor is the CRU noise. The changes that were implemented for Set 2 were based upon analysis of the data from Set 1 and were limited to those items that could be readily implemented to qualitatively reduce noise. A significant reduction in the component noise levels have been made. When performance testing Set 2, no measurements of noise level were made. To the naked ear, the noise level of Set 2 has been reduced significantly over that of Set 1. Although improved, the CRU hotwell shell still appears to be acting as an amplifier such that the Set is not sufficiently quiet to meet the specification. The improvements need to be carried further to reduce noise to an acceptable level.

Since the notwell shell was responding to the rotating assembly imbalance, a significant reduction in the amount of imbalance would also help to reduce noise. Consideration was given to both improved low speed balancing and balancing at speed. For Set 2, the low speed (~2000 rpm) balancing was improved from 0.002 to 0.0002 in-oz imbalance. Though not employed, further improvement would be made by balancing at speed at this sensitivity.

OFFSET GEARBOX

Four gearbox design approaches were considered as presented in Table VI-A. The Berg sprocket belt driven gearbox is shown as an example in Figure VI-B. Each gearbox was installed in Set No. 1 and tested with a microphone located at the center of the condenser louvers 3 foot from the Set on each side. The following data are attached:

Table VI B. Gear and Belt Data

Figure VI-9 Gear and Belt of 4 Plot (worst case)

Table VI C Belt Data

Figure VI 10 Belt do f Plot (worst ease)

Table VID Bierg Data

Figure VI 11 Berg db f Plot (worst case)

Tuble VI-A Gearbox Design Approaches

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Type	Gear	No. Teeth	Pitch dia.	Speed (rpm)
Spur (Set 1)	1	61	1.906	3450
	2	42	1.312	5010
	3	46	1.437	4575
	4	75	2.344	2806
Belt Drive	1	18	1.375	3450
	2	12	.764	5117
	4	22	1.401	2820
Berg Drive	1	22	1.162	3450
	2	15	.812	5057
	4	28	1.462	2710
Helical	1	85	1.906	3450
	2	60	1.348	4887
	3	66	1.480	4443
	4	105	2.358	2792

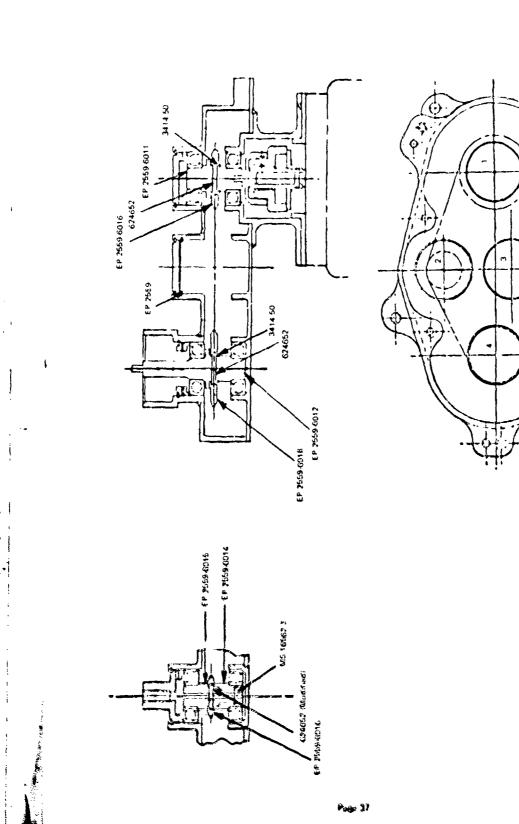


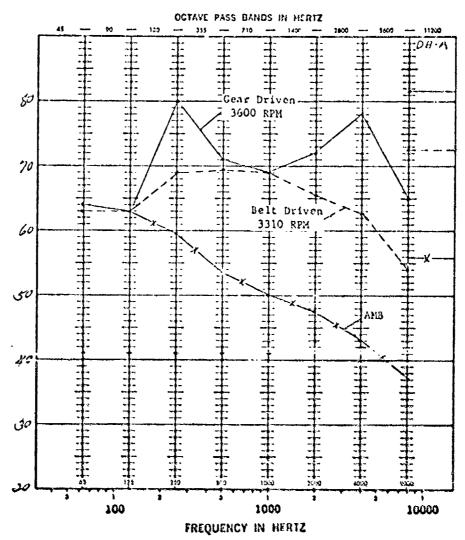
Figure VI-B. Gnathor Anumbly, Belt Driven EP 2559-60

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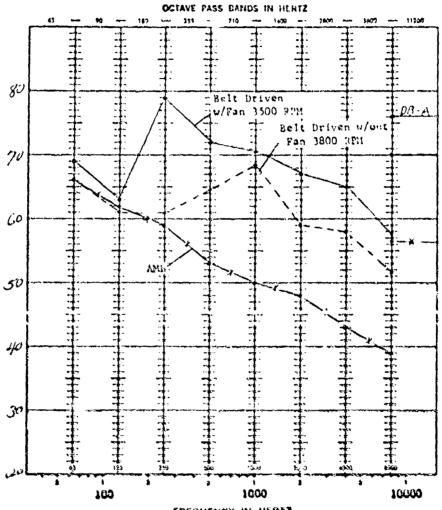
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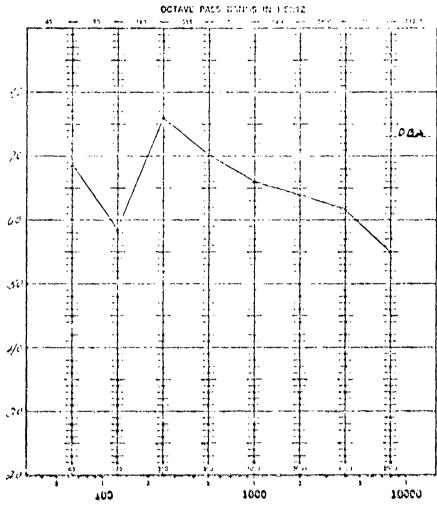
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Figure VI-11 Berg th-F Plat (Warst Case)

Table VI-E Helical Data

Figure VI-12 Helical db-f Plot (worst case)

From these tables and figures, Table VI-F (summary of the peak db for each location and ranked from (1) the quietest to (4) the noisiest), and Table VI-G (summary of the selection tradeoff), the selection of the Berg version was made. This gearbox is shown in Figure VI-13.

While limited noise data was taken on the variable speed gearbox, the levels were considerably lower than for any of the above. It is also buried in the lower compartment of the Set and no improvement in noise was attempted although, based upon the desirable results of the constant frequency offset gearbox, significant improvement could be made.

CRU (COMBINED ROTATING UNIT)

The redesigned CRU is shown in Figure VI-14. Because the turbine balance assembly is installed in the hotwell which is made of thin gauge material for minimal weight, it is capable of acute vibration. Simultaneous with the relocation of the pitot pump from the forward to aft end of the assembly, the turbine wheel overhang was reduced.

Critical speeds were determined by an analysis which includes the gyroscopic effects and the spring mounts (bearings) for any spin to whirl ratio. Also a normalized mode shape of the shaft deflection is given for each critical speed.

Utilizing a spin to whirl ratio of 1.0 (synchronous whirl) and bearing stiffnesses of 250,000 lb/in for each bearing, the first three critical speeds were calculated for seven configurations. Table VI-H shows critical speeds and mode shapes for each configuration.

In order to push the critical speeds out of the operating range either increasing the shaft thickness (new bearings) or decreasing the length of the overhang could be incorporated. If 0.2 inch is removed from the turbine overhang end and 0.25 inch removed from the pump overhang end, the critical speed is pushed up to 58,000 rpm (Configuration 6). With a titanium pump housing the critical speed is 63,000 rpm (Configuration 7).

Configuration 7 was selected with a slightly smaller pump overhang so that the bending critical speeds at both turbine and pump end are 65,000 rpm. This is 18% above the 55,000 rpm operating speed and is considered sufficient, though in the long run slightly more margin is desirable. The turboalternator is shown in Figure VI-15.

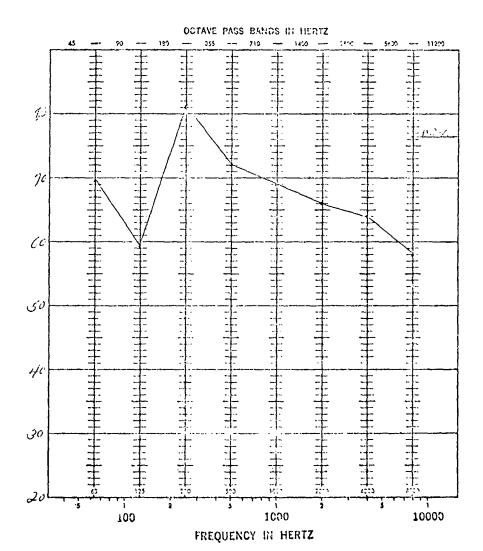
After this redesigned CRU was fabricated, a series of development tests were conducted using gaseous dry nitrogen as the test gas. With the redesigned nozzle plate (EP2659-1228A) in the as-received condition, stall torques were measured and compared to the original (Set No. 1) nozzle plate and the test plate (flat plate) used as a basis for establishing the nozzle spacing, This data is shown in Tables VI-I and VI-J which revealed poor performance. Consideration was given to possible manufacturing error so the drawing and hardware were examined for possible discrepancies, e.g., nozzle overlap, nozzle-blade gas impingement, nozzle profile, and blade-diffuser impingement. Multi-size layouts and shadowgraph tracings of the hardware were made which indicated that the new nozzle plate is dimensionally as accurate as the previous ones. One possible improvement would have been slightly greater nozzle-to-blade height lap ratio. A series of spin, flow, and acceleration tests were made; data shown in Table VI-K. The conclusion from this testing is that the as-received

Page 44

Table VI-E Helical Data

ITEM	•		`			ĭ	ST AND	TEST AND EVALUATION DIVISION	TION DIV	NOISI/				TEST NO			
7.7	1.5 KW RANKINE W	ANK/N	100	}	U.S.	U. S. ARMY MOBILITY EQUIPMENT RESEARCH AND	MOBILIT	Y EQUI	PMENT	RESEA	3CH AN	۵	ŝ	SHEET		- 0F	
MEL	MELICA GEAR BUY	48 BC	7	ı			DEVEL	DEVELOPMENT CENTER	T CENTE	ER			<u>۵</u> 	DATE -	70cT 211	77.5	
EIFGR.	EIFGR. SILWDSTRAM	STRAN		ţ		5∡	RT BEL'	FORT BELVOIR, VIRGINIA 22060	IRGINIZ F	A 22060			,	JOB NO.	7. 2%	T. 24 - 39	
MODEL NO	NO.			J	000	OCTAVE BAND SOUND DRESSURE / EUTES	NO 50	1 0 11	100000	11 300	\$ 12/112			RECORDER	IM	I.M. KIGHIS	2.5
SERIAL NO.	. NO.			j		0	B RG	OB RE C. COO JMICKING	12 00'	1/68/1	040	.	ö	OBSERVER		R. L.	
REF: _				j													
:NST. 💠																	
Ervo F	TEST 817.	2.77.2	LAR	AREA	FLOG	LAR AREA PLOG 323 MICROPHONE LOUNTED CENTER OF LANDED	M1 C.P.C	PHON	7 7 3	4760	CENTE	0.66	020.777		Fr of Floring Providence	P-111	0000
37.2.15									-				77	1	-	7.7	
STA																	
Ö		1	8	*	8	•	7		•	2	=	22	2	2	2	2	2
	OCTANE BAND	BAND															
	CONTER	FREG	RIGHT		LEF.7	CHITRO											
	WE		510€	REAR	3015	1-11:10											
				4	e)	*											
	63		61.0	61.5	58.0	5.67											
	125		640	61.5	61.5	59.5											
	250		720	78.0	12.5	81.5								-	-		
	200		71.0	720	72.0	72.0							-				
	8		70.5	72.0	70.0	69.0											
1	000		10.5	01/10	180	100		-							-		
-	9000		67.5	037	67.0	64.0				-						-	
	8000		61.0	630	11.0	58.0											
			100	•		,											
	K		27.0	2/10	X1:0 18:0 X2.0	200	1			1	1	1					
	A-80		76.0	18.0	76.0 78.0 25.5 71.5	27/2			1		1			1			
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_								İ									
MOTES																	
	000																

STEFB Form 28 28 Jun 72



Position # 4

Control Panel 1.5 KW Rankine w/Helical Geors Mfgr. Sundstrand Test Conducted 17 Oct 74

Figure VI-12 Helical db-f Plot (Worst Case)

Table VI-F Data Summary

·		Table V	/I-F Data	Summary			
Octave Center		Right		Left	Control		
Hz		Side	Rear	Side	Panel	Avg	Rank
	Belt Drive	66.0	69.0	69.0	67.0	67.75	4
63	Berg Drive	61.5	59.0	57.0	68.5	61.50	1
	Helical Gear	61.0	61.5	58.0	69.5	62.50	2
	Spur Gear	65.0	64.0	66.0	65.0	65.0	3
	Belt Drive	€3.0	63.0	63.0	64.0	63.25	3
125	Berg Drive	60.5	60.5	60.0	58.5	59.875	1
120	Helical Gear	60.0	61.5	61.5	59.5	60.625	2
	Spur Gear	63.0	63.0	64.0	63.0	63.25	3
	Belt Drive	71.0	79.0	73.0	74.0	74.25	3
250	Berg Drive	72.0	74.5	72.0	76.0	73.625	1
250	Helical Gear	72.0	78.0	72.5	81.5	76 0	4
	Spur Gear	72.0	0.08	70.0	74.5	74.125	2
	Belt Drive	70.U	72.0	70.0	68.0	70.0	2
	Berg Drive	70.5	71.0	71.G	70.0	70.625	3
500	Helical Gear	71.0	72.0	72.0	72.0	71.75	4
	Spur Gear	69.0	71.0	68.5	67.5	69.0	1
	Belt Drive	58.0	70.5	69.5	67.0	68.75	2
	Berg Drive	69.5	70.0	69.0	66.0	68.625	ī
1000	Helical Gear	70.5	72.0	70.0	69.0	70.375	3
	Spur Gear	67.5	69.0	70.5	68.0	68.75	2
	Belt Drive	64.0	67.0	€7.0	64.0	65.5	1
	Berg Drive	67.0	68.0	66.5	64.0	66.375	2
2000	Helical Gear	70.5	71.0	69.0	66.0	69.125	3
	Spur Gear	72.0	72 0	71.5	67.0	70.625	4
	Belt Drive	62.0	65.0	66.0	62.5	63.875	1
	Berg Drive	64.5	66.5	65.0	61.5	64.375	2
4000	Helical Gear	67.5	69.0	67.0	64.0	66,875	3
	Spur Gear	82.0	78.0	74.5	71.0	76.375	4
	Belt Drive	54.5	57.5	58.0	55.0	56.25	1
	Berg Drive	54.5 58.5	60.5	58.0 58.5	55.0 55.0	58.2	5
8000	Helical Gear	61.0	63.0	610	58.0 58.0	60.75	3
	Spur Gear	63.5	65.0	65.0	61.0	63.625	4
	Belt Drive	76.0	80.5	78.5	77.0	78.0	3
	Berg Drive	77.0	78.0	76.5	77.0 78.0	77. 3 75	1
A-P	Helical Gear	77.0 78.0	81.0	78.0	82.0	77.375 79.75	3
	Spur Gear	83.0	83.0	80.0	78.0	81.Q	4
	Belt Drive	72 0	76.0	74.5	72.\$	73.75	1
	Berg Drive	74.0	75.5	74.0	73.0	74.125	2
DB-A	Helical Gear	76.Q	78.0	74.0 75.5	75.5 76.5	76.5	j
	Spur Gear	83.0	81.5	78.5	76.5 75.0	79.5	4
	apur atar	09.0	gra	70.0	73.0	, y. Q	7

Table VI-G Selection Tradeoff

The second the second s

<u> 53-</u>	3000 Hz	Belt	gerg	Helical	Spur
Tim	es 1st	11	14	2	8
	ies 2nd	11	12	10	2
	es 3rd	5	6	12	9
	res 4th	5		8	13
		5 <u>5</u> 32	32	8 32	1 <u>3</u> 32
A-P	·				
Tin	nes 1st	2	2	0	0
	nes 2nd	1	2 2	1	1
	nes 3rd	1	0	3	0
Tin	nes 4th	0	0	$\frac{0}{4}$	3
		0 4	0.4	4	4
<u>ОВ</u>	A				
T in	nes 1st	2	2	ე	O
	nes 2nd	2 2	2 2	0	0
	nes 3rd	0	0	3	1
	nes 4th	<u>o</u>	0	1	3
		4	0 4	4	3
	ır. Consum(ption	5001	240	252 220
	watts)	280	262%	246	252-270
(T)	sken on #1	Unit)			
	lection		u		
	ased on lov		×	×	
8	lased on lov	vest power		^	

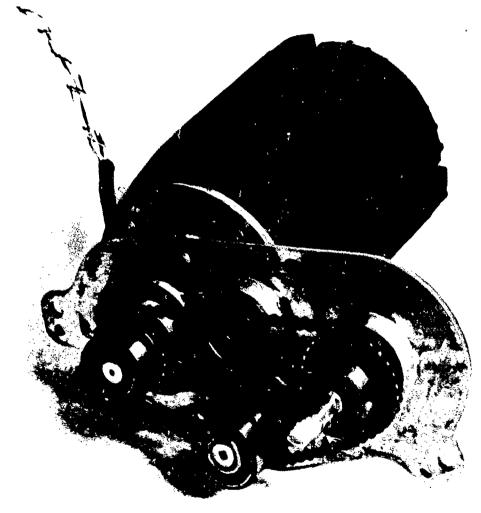
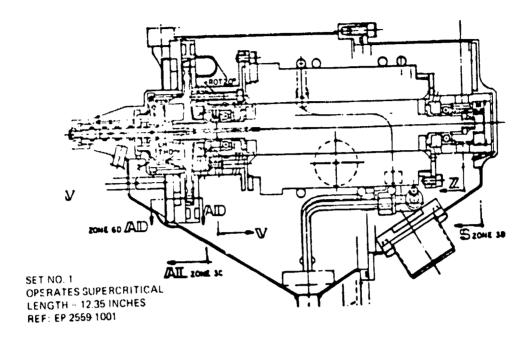


Figure VI-13 Constant Frequency Motor and Office Gazrhou



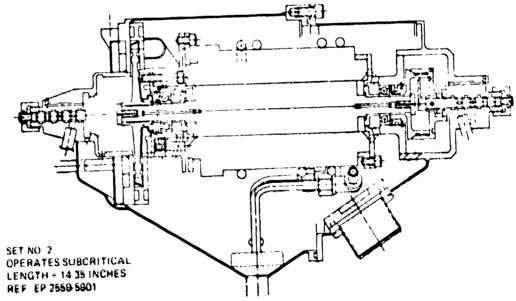
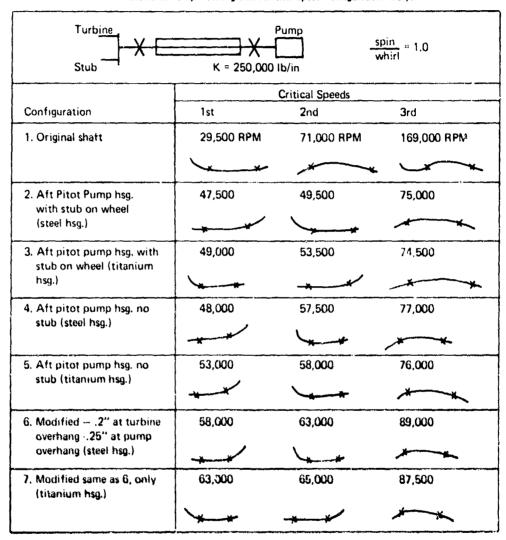


Figure VI-14 Set No. 1 and No. 2 CRU Configurations

Table VI-H Turboalternator Pump Rotating Shaft Critical Speed Configuration Analysis



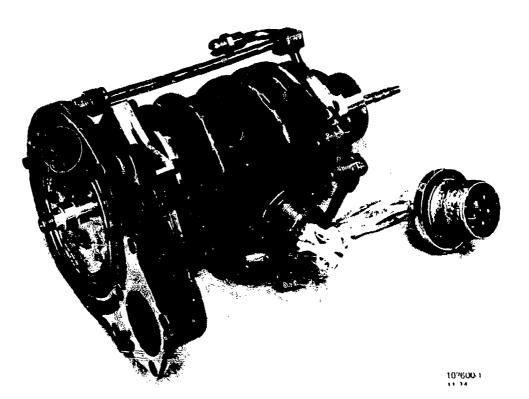


Figure VI-15 Turbo Alternator Pump Assembly

Table VI-I Summary of Stall Torque & Spinup Data

Nozzle	No.	PNI	Τq	w	Ax.	PNI	
Plate	Noz.	(PSIG)	(in lb)	(lb/sec)	CI.	@ 55K	Comments
Original	9	1350	12	.094	.034		
(Wide Spaced)		1250	10.5	.033	.034		
EP 2559 1228		850	7	.061	.034		
		1250	13	.069	.020	660	Flows may be
		830	8	.045	020	₩ 52000	questionable?
		1350	13	.093	.010		
		1250	12	.088	.010		
		850	8	.061	.010		
	4	1310	7	.035	.020		
		1250	6.5	.034	.020		
		850	4	.024	.020		
Flat Plate	10	1250	16.5	.110	.020	400 @ 57000	
(Close Spaced)		800	10.1	.068	.020		
EP 2559 1270	7	1200	11.3	.074	.020	480 @ 56,500	
		850	7.5	.049	.020		
	5	1215	8.?	.052	.020	580 @ 56,000	
		850	5.8	.036	.020		
Latest (A)	10	1350	11.5	.094	.020	750 @ 60,000	(Run 203) with
(Close Speed)		1200	9.5	.082	.020	,	204 PP Hts
EP2559 1228A		850	6	.058	.020		
003 CRU	7	1350	7	.063	020	800 @ 54,000	(205)
002 Exh. Hsg		1200	6	.056	.020		
5 17 74		850	4	.040	.020		

Table VI-J Nondimensionless* Stall Torque Data Using GN₂ (Des. PR = 529 @ AR = 25)

Noz Plate	No.	Meas. A.R	Pin (PSIA)	PA.	r cale.	r mess.	*	Cale in	*L	<u>c</u>
View										
P2550 1228A	10	26.6	1365	84	.6582	,5195	76	\$045	77	04.00
			1395	84.5	.6585	5382	81	5801	90	£ e † e .
			1265	115	6690	5727	25	5668	84	
	7	25.4	1365	88	.4677	.4616	30	4199	64	26
	5	26.1	1370	90	.65.12	5726	88	6783	184	
	•	••••	1365	182	6755	\$805	87	A023	104	
ila I										
P2568 1270	10	12.6	1265	76	6831	6376	92	7166	1-34	
	7	12.45	1215	76	5847	6426	92	1260	106	
	\$	12.4	1230	51	88 42	6681	94	1200	107	
Designation										
925A9 1320	9	17.2	1365	22	6615	519 ?	€1	£486	#7 3	
	4	18 \$4	1326	30	era)	843	120	1641	114	Cheklain olid data
1291 <u>9</u>										

Table VI-F. CRU Test Date

Test	Run			No	PSIC	PSIA	PSI	•,	May/ MARIL	Avg. eafé	
Dete	No	A Alba	Config	Nes	PNI	FMR	1.9e	THE	**	mess	Commont
			44W				£10005			theo	
6 4 74	2018	Spin	1228A	t.;	824	Ourt	# 5	42			No primp hos
No Fump			903 CMP								Herry # 52 Kipm
Hin	503	Same	003 CBG	10	(KIA)	Duel	8.5	RO.			Money & 52 Kipm
	210	et sin	003 CDB	10	641)	Duct	ЯS	63			AS) Kilbiu
	211	AL + x1	ON CHILD	163	640	Ourt	3	43			RE) Kippen
	212	Acces	BO2 CRU	10	1 360	Dist	10 *	70	COUN		Så Kipan
6 6 74		Flore	002 CPU	10	65O	ነኝ ወን	9 trans	65	044N		Cali. W - 047 % Cat : 92
ter briud							i i gage		0467		
Hug		Fluor	ODS CMD	10	R50	15 28	12	65	OSE	Calc	Cate W - DA*1 % fv1 - 31
							! ច		Q# /		
		2 Harde	002 CAU	13	1250	16.06	18	65	02:16		Cate W + 0891 € Crt + 94
		_		_			2.1		0972		
		f Hery	(XIZ CRU	3	ntill.		**	44	02// 0331		Ca - f ta
	213	Act es	003 C40	14	1.2%0	Dust	1	12	are	4	\$2 Kepse
	214	Accel	ESIZ CHU	10	1250	6 A	7.75	15	UKI	97	69 5 Kipm PH - 1 31
	21	Ac cel	BD2 CRC	10	1250	9 20) 25	15	067		67 5 Kipm
	.116	A _{id} c.e)	20,080	2	145	4 1	3 6	15	023	102	W Caic - 020 PR - 10 Cit - 1 10
	21 /	Ayrad	GE2 CHU	}	1 349	(Sec.)	3 6	**	023	94	62 5 Killion Care 102 52 Kiljion
						ten U	nac t				
6 10-74		Berteber Kark	1228A			- Jug	71,				
		Protect	ひりょ じゅい	5	660	3.	049				Pa 38 85-14 (PS)-1
					5/50	:	147				
					1260	*	244				
					1 36:03	5	244				
				10	£150	15	36 j				74m-e-5 2
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					1250	252	1215				
					تقافر ا	3.0	12				78-92 44 11-44£ £3-69
					1250	2	1 2				
					a ⇔	1 8	ದರ				

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				Table	VI-K	CRU Test	Data (Cor	st.)			
Test	Pun	Turne	Cuetia	No.		PSIA	PT502	۴.	15. 361.	د	
Pese_	He).	TYPE				<u>Penh</u>	4.6	THE	PT502	P100075	Comments
6-10-74	218	Spin	003 CBD ~1138¥	3+2	850	Duct	4.3	\$7	.014		Cd+1.17 62 Repm
		Flow	-	-	160	•	1.9	\$#	.0121	(1250)	C4-1.17
					1140	•	7.1	-	.0574	.057	Cd-1 29
					65 0	•	1.1	54	.024#		€4=1.11
	219	spin	•	2	640	-	. 15	51	.00824	•	C34×.80 《印 東京集業
		Flore			9:40	-	. \$	-	.0115		Cit+ 96 45.5 \$85#
6-12-74	720				1150	_	, 9	,	.931		.020 W thee
W-12-74	<i>,</i> 20	ន់ផ្ទះ	Ant L		67 0		•)O Krim
			teak Ring	10	1000	•	14.6				42 xrpm 10 % in-15
			Found L	oaky P	भाग्य भिन्न	Naun ing					gt al 1
6-11-74		Stall	-1228	10	#50	Duct	10.7	€0			6 in-15
			052 CM		1250		£" #	41			10 in-1b
			Anti	. 5	# 5 0	No Duct	3,75	60			4 in 15
			Leak	3 • 2	1250		5.61	6.2			6.5
			is Turk		#50	Duct	1.75	6(*			4
		stall	-1.119		1250	:	5,61	42			6.5
			-122 9 302	5	K50).75	62			4
		,	102 No	10	NSO		5.6) 10.4				6.25
			M1145		1250	•	15.9				£ 10
		Stail		10	010	•	10.4	-			• 10
			303		1250	•	15.9	-			10
			No Miraj				•••				••
	221	Accel	•	-	-			•			
	222		ii i ma		-			-			Identical
	•		-11-19							in-	ghturb
										tb Ed.	
6-24-74		Stell	-122ma	,	850	Duet	_	50	.0177	3	
Fe=20.45"		_	903 CBO		1240		75 1.37	£0	.0264	4.75	
4 14.41 F		-	Block	3+2	650			57	.0262 .03 6 0		
Fost flus	A				#64 1140		7.12 2.62	\$60 55	.0360	3.5	
With Nos. Fit & Ind	11.4			3	1210		\$.65 5.65	EU	,025 545) . 10	
Nos. W ca				5×2	££13		6.9	22	. 19 5 19 5		
	•			•	1200		13.1	£9	.6729	Lú. 16	
		-	•	16	650		14	55	044	7	
					1150		46	63	. 103	14	
		-	•	4	650		. \$	60	0100	1.5	
					64.1		, 7	€3	.0145	4 4	
					1130		4.00	62	. 0264	3.0	
					£50	3.8	. \$	6.2	.0150	1 75	
					250	2.5	. 3	6.5	0145	2.5	
					1100	3.5	1.05	45	.0204	3.75	
	235	P treit	*	4	4.55 E 5	3 3 =36.2	1.65	ŧä	5264		
		24411	•	2=2	والجاع	5.6	3 . bã	\$ €	.6≛0	4.75	
					e4 3	4.4	*	ę s	0366	6 .0	
					ļļtē	6.3	Q. W	76	. 253	₩.25	
	244	Accel	٠	•	licé E u	6.1 1 24	6.2	76	. 86 3		
			•	,	650	, 	1.6	εô	. 8 1948	6.25	
		= 4411		,	656	E. 3	3.4	65	.0636	8.5	
					.114		12.5		.gre	10.5	
	++4	Accet	•	•	\$\$15	Ģ. 3	12.5	43	.870		
					F6 −:						
D. 26. 34		مدعتم	•	•	419	Share #					ti tra
日175で発	23E 227	44	•	ţe.	479 990	Suct	•				it drem io. i drem

nozzle plate was not adequately clean and installing flush parts to clean the nozzles was sufficient to enable predicted performance to be achieved. There was still a discrepancy between measured and calculated flow through the nozzles so wifer brass plugs were installed in place of the steel plugs to minimize leakage that might escape through the flush ports. The resulting non-dimensionless data is shown in Table VI-L and Figure VI-16 from which it can be seen that reasonable correlation to prediction exists.

VALVES

Three hot gas solenoid valves are used in the Set, one shutoff and two control valves. Two designs were tested, one designated AG56C-21 and the other GA-17310. Both are pilot actuated valves with the former being significantly smaller, lighter in weight and more leak tight than the latter. This valve is used in Set No. 1 and often experienced sticking. They were replaced with the GA-17310 valves which cycled well (except at low voltage conditions).

For Set No. 2 both valves were modified. The AG56C 21 internal clearance was increased. The GA-17310 valve was modified for a Hastelloy 25 seat and a Stellite 6 hard facing over 17-4 PH poppet for better internal leakage and long term endurance. The solenoids of both were also increased in size for higher pull-in power at lower voltage.

The GA-17310 valves are used in Set No. 2 and have performed flawlessly during testing.

PITOT PUMP

The Set No. 1 pitot probe (EP2559-1148) operared at 28% efficiency (reference Figure VII-9), and was internally milled and externally shaped by hand. In an effort to reduce the cost of manufacturing the Set No. 2 pitot probe (EP2559-5969) was stamped internally and milled to shape externally with minimum hand finishing. This accounts for the more simplified shape of this probe. Rig tests showed little difference in performance between the long and short nose versions of a given configuration so the Set No. 2 probe was made with the short nose. Little difference was intuitively expected in efficiency.

BOOST PUMP

The boost pump (Micropump Model 10-90-316-961) supplied with Set No. 1 included a 2-fluted inducer. The pump showed difficulty in priming and operating at a low NPSH. It was concluded that an improved pump would be desirable.

For Set No. 2, two other configuration pumps were tested. One was a Micropump Model 10-90-316-961 modified with a single flute. This pump experienced less difficulty in priming and was able to pump its rated capacity down to 9.5 psia where the pump lost unime.

The other configuration puling tested was Micropump Model 12 00-303-763 gear pump modified with an oversized (3/8" diameter) inlet. No difficulty was experienced in priming under very low conditions of NPSH and the pump exceeded capacity requirements in both head rise and flow. The pump was tested under simulated conditions in the hetwell with CP-25 as the working fluid down to NPSH = 0.73 psia and an inlet head of 4.5 inches. The pump performed satisfactority under these conditions and was able to execute a series of starts and stops without losing prime. The pump characteristics are shown in Figure VI-17.

GN ₂ Accel Data	21	Voz	3+2 Noz	5+2 Noz	
Speed (Krpm)	35		50	50	
PR	38	2	232	166	
Timeas (ft lb)	.21	18	.301	.411	
T Pred (ft-lb)	.17	71	.313	.445	
meas (lb/sec)	.01	17	.049	.071	
pred (lb/sec)	.01	17	.039	.057	
meas	.58	37	.288	.275	
pred	.57	74	.358	.342	
pred	.44	18	.373	.370	
GN ₂ Stall Data	PNI (Prej	T (Pre)	PNI (Post)	<u>T (F</u>	
2 Noz	840	2	1060	2.	
	1190	3			
5 Noz	650	3.5	1060	6	
	1240	7.4 - 8.3			
7 Noz	660	4.75	1018	8.5	
	1200	10 4			
10 Noz	650	7	1000	12.9	
	1150	14			

390 PSIG @ 50.5 Krpm

500 PSIG @ 61.5 Krpm

480 PSIG @ 57 Krpm Post Brass

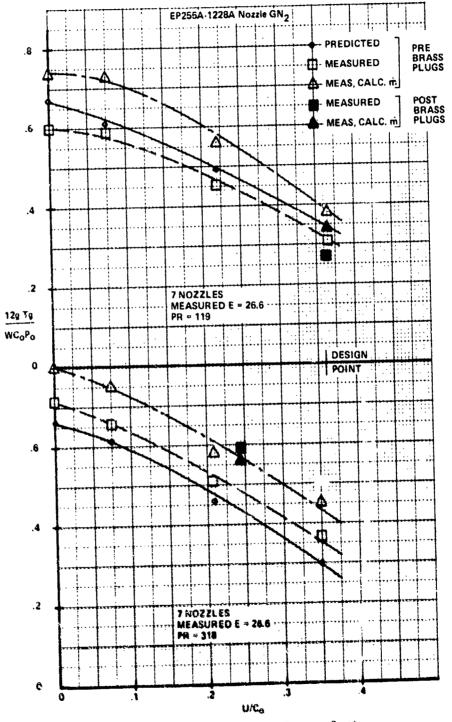


Fig. 14 VS-VS Nondimensional Torque vs. Spend

Page 58

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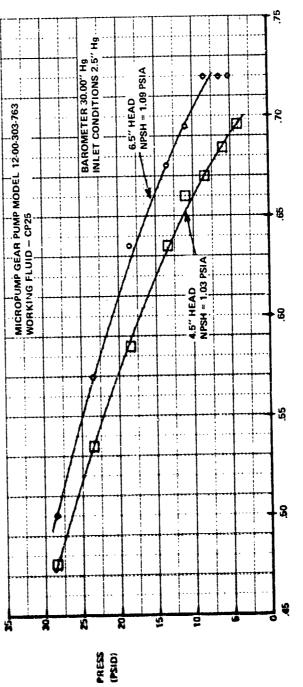


Figure VI-17 Pressuse vs. Flow FLOW (GPM)

There are conditions in the set where the NPSH could be on the order of the height of the fluid over the inlet of the pump. The worst case occurs at shutdown or during a load reduction where the condenser fan cools the condensate to a temperature below that of the fluid in the hotwell. Under this condition the saturated fluid in the hotwell will boil. To ascertain the capability of the 12-00-303-763 modified configuration pump to continue to pump, this condition was simulated using water in a bell-jar and pulling vacuum until a rolling boil occurred. Visually, it was observed that pumping continued.

It was decided if even a slight amount of subcooling could be done between the hotwell and the inlet of the pump, that some positive margin in pumping characteristics could be maintained. A calculation at a 160°F hotwell temperature and 100°F air temperature surrounding the 3 inch + transfer tube indicated that by finning the tube, 2°F of subcool could be induced.

The cooling fins and the as-described modified gearpump were selected for Set No. 2.

START APPROACH

The Set No. 1 start approach depends upon an accurate measurement of the heater fluid temperature to trigger the opening of the shutoff and control valves. With the accumulators in the system to absorb the expanding fluid backflowing from the heater, system pressure would build up as the temperature increased. When the temperature and pressure are in the vicinity of the design point, the valves are signaled to open and the turbine would accelerate to control speed in a matter of seconds.

The heater outlet is at the high point and so the control thermocouple was placed at the outlet under the hypothesis that the hotter fluid would migrate there. The result was that with the valves closed during the heatup period, the thermocouple was not sufficiently buried in the heater to be exposed to the maximum temperature of the fluid. Overheating of the fluid during startup could occur and was prevented by premature manual actuation of the valves to expose the thermocouple to flowing fluid. Only then did it accurately register the temperature. To rectify this condition for a satisfactory automatic start approach for Set No. 2, the following was considered:

Construct new heater with buried temperature sensors.

Sense heater inlet to pick up the temperature of the fluid backflowing out during heatup.

Cycling the start flow valve to intermittently expose the outlet thermocouple to hot fluid.

Use pressure as an indication of the start signal.

Bootstrap or assisted bootstrap start of which there are a variety of techniques.

Any of these approaches required a change to the controller, Additionally, an important consideration was the differences in complexities between the various methods.

Tests were conducted at MERDC on Set No. 1 modified for a start pump assisted bootstrap start. These were not fully automatic starts but were manually assisted. This data is presented in Figures VI-18, VI-19, and VI-20. These simulated starts are acceptable. A plot of pump pressure (pitot pump against that used on Set No. 1) vs. speed (Figure VI-21) implies that the pitot pump will overcome the start pump at about 115 per and 21,000 rpm.

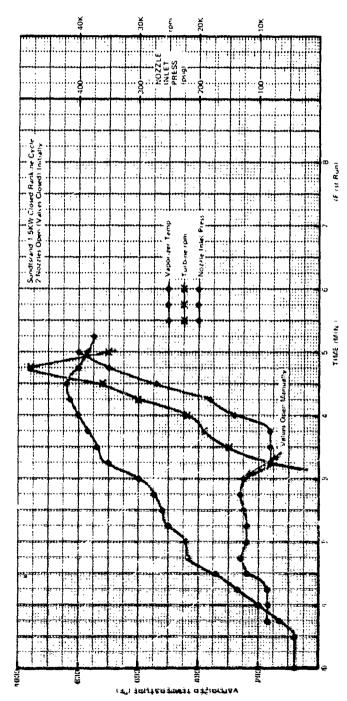
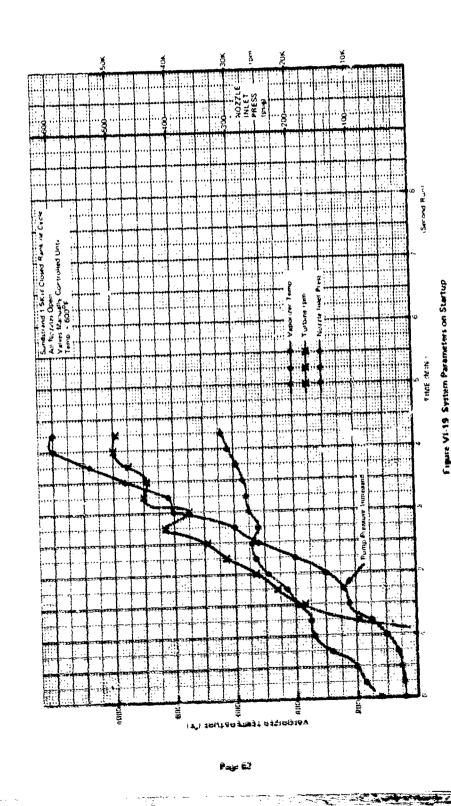


Figure VI-18 System Parameters on Startup



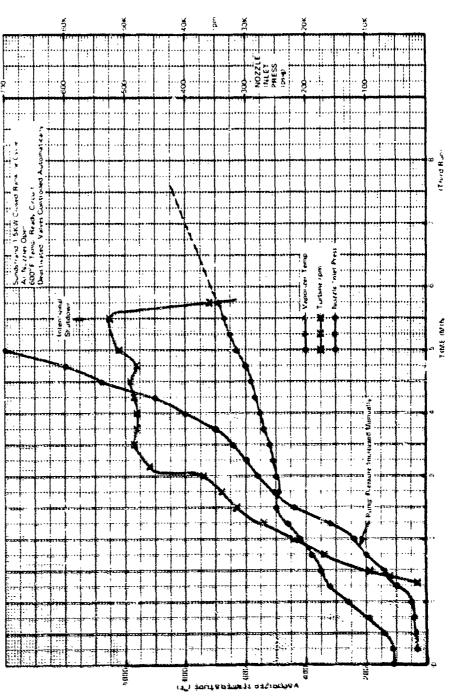


Figure VI-20 System Parameters on Starrup

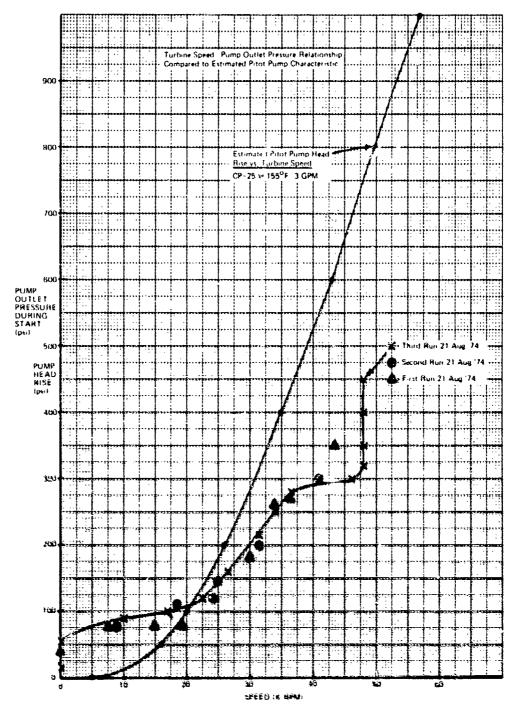


Figure VI-31 1.5KW GRC Bretiting Start

These tests provided justification to switch to a start pump assisted start approach using a pump with sufficient margin to provide the required pressure at 10 nozzles worth of flow. A calculated flow value of about 0.1 gpm as a minimum would be necessary to be provided by the start pump.

Two Wankel rotor pumps were tested; data is presented in Figures VI-22 and VI-23. At the risk of being oversized, the P260 pump was selected due to the marginal head rise of the P193A1 pump. The finished hermetic assembly is shown in Figure VI-24.

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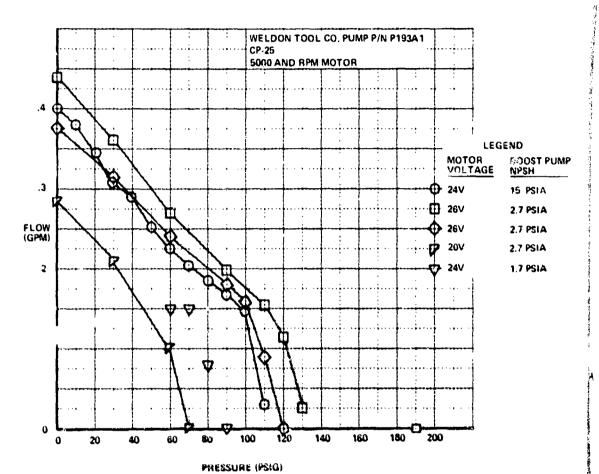


Figure VI-22 Performance Test

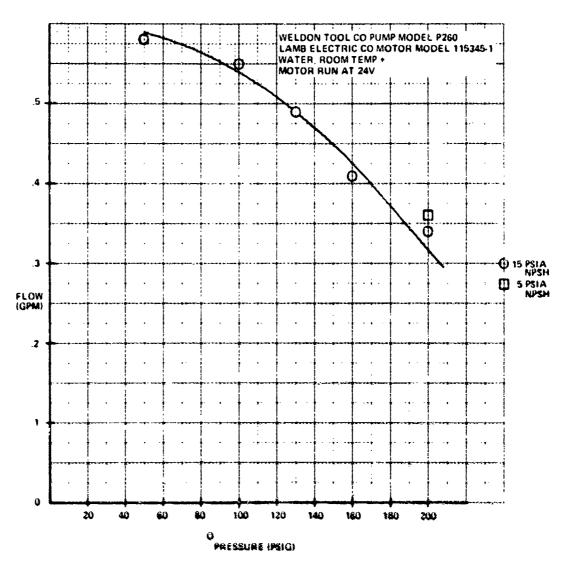


Figure VI 23 Perfumaçõe Guave

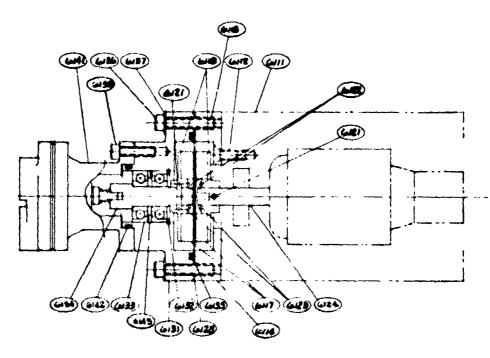


Figure VI-24 Start Pump, Coupling, Motor Assembly Ref. EP 2659-I 101

SECTION VII
SYSTEM DEVELOPMENT

Unit No. 2 was tested as a complete packaged system except that the control box was not installed and an external power supply vias used to operate the start pump and several parasitic loads. Figures VII-1 through VII-5 are various views of the $2' \times 2' \times 2'$ system.

Thirty (30) tests were conducted at Sundstrand and sixteen (16) conducted at USAMERDC laboratories which form the basis of knowledge about the system at this writing. Throughout the test program several changes were made to improve operation. Figure VII-6 is a schematic which represents Sundstrand post iRun 017 tests while Figure VII-7 in a update illustrating changes made at USAMERDC (most of these changes were made prior to 6-20-75).

Test data is illustrated in Table VII-A (Sunds, and tests) with data analysis illustrated in Table VII-B. Table VII-C lists data and analysis conducted on the Set at USAMERDC. The results of these tests indicate that the Set is not producing the required amount of output power. The following discussion elaborates on this result.

The changes made between Frees VII-6 and VII-7 were an artempt to isolate possible heat shunts to ascertain any effection or ower. These included the following:

Two of four condenser drains capped to induce the condensate to drain through two active drains.

Hand valve installed in the one of two active drains which dumps condensate into the hotwell close to the exhaust housing.

The regenerator condensate drain closest to the regenerator vacor inlet port had a hand valve installed.

The effect of these with and without the valves open did not materialize in any obvious change to the output power. In addition, the hotwell was modified so that condensate would drain through the main hotwell into a modified hotwell. This also had no noticeable change in output power. Other differences between Figures VII-6 and VII-7 are immediately downstream of the start and pitot pumps to gain knowledge about automatic start characteristics.

STEADY STATE OPERATION

Figure VII-8 summarizes the original design point performance. Review of the Tables VII-A, B, and C indicates that the data falls into two categories:

Data at greater than design turbine inlet pressure (PNI)

Data at greater than design turbine outlet pressure (Pc + Δ P \approx Pc + .3)

This partly, but not fully, explains the low power. Other contributing areas are summarized as follows:



Figure VII-1 Set No. 2 on Test Stand

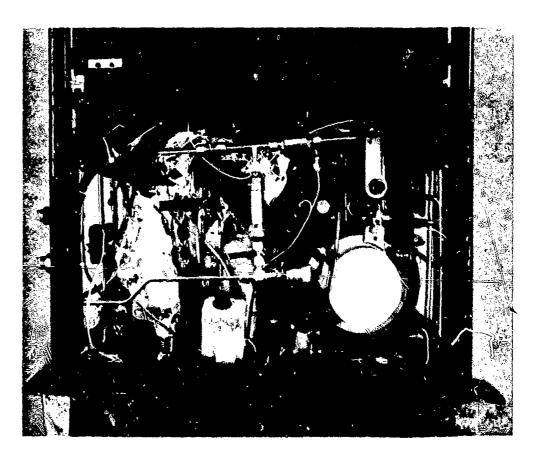
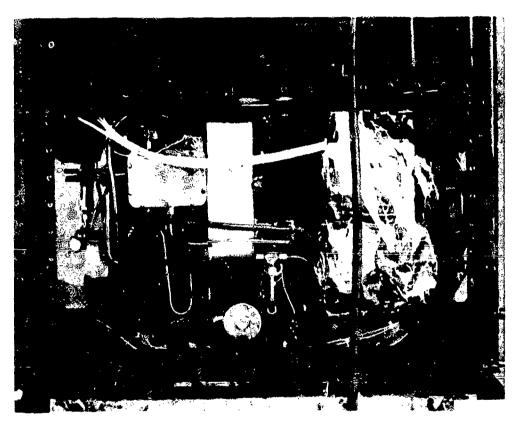


Figure VII-2 Set No. 2 Front Door Open



Figore VII-3 Set No. 2 Right Side Panel Removed

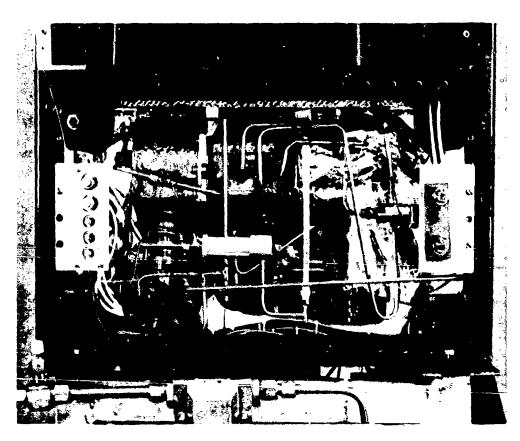


Figure VII-4 Set No. 2 Left Side Panel Removed

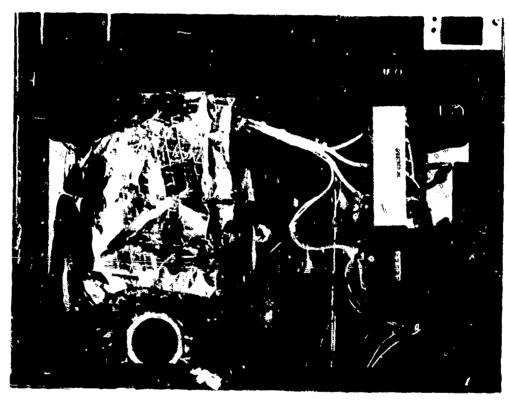
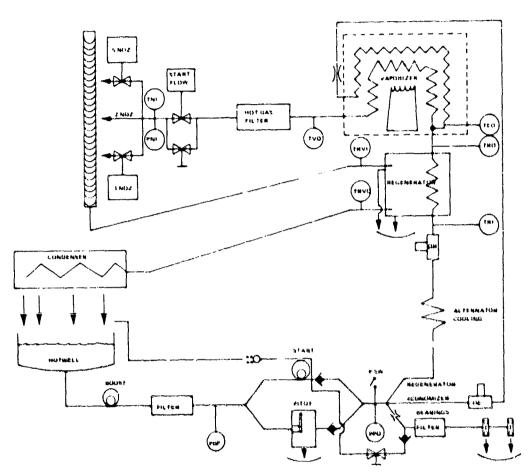


Figure VII-5 Set No. 2 Back Panel itemored



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Figure VII-6 1.5 KW MERDC Functional Schematic (Post Run 017)

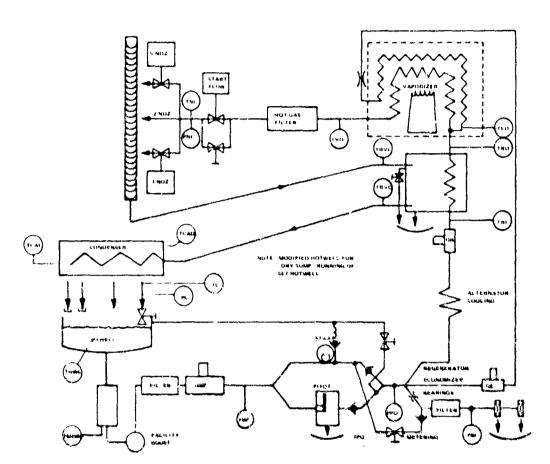


Figure VII-7 1.5 KW Closed Rankine Cycle Functional Schematic

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Figure VII-8 Original Design Roint Partormani

	(1)	(2)	(3)
	Set 1	Set 2	Design Pt.
Heater efficiency	.88	.8284	.88.
Regenerator effectiveness	.80	.6974	.855
Pitot pump efficiency	.28	.124165	.35
Turbine Efficiency	.31	(1) (2) (3)	.62
Heat Shunts	Not considered ?	0	

The quality of the data on Set 2 exceeds that on Set 1. Nonetheless, it appears that heater and regenerator performance is down slightly. This may be due to manufacturing QC for the heater and either core to housing fit and/or slightly undersize for the regenerator. These can be controlled at the design level and do not represent an R & D effort.

The expectation for 23% pitot pump efficiency for Set 2 was based upon the data obtained for Set 1. This is shown in Figure VII 9 along with a plot of Set 2 pitot pump power consumption. The Set 2 pitot probe was designed to be more cost effective than that of Set 1. These differences are elaborated upon in the improvements section.

The turbine performance of Set 1 was low primarily due to the separation distance between the nozzles. The efficiency of the turbine of Set 2 was investigated in several ways. The data of Tables VII B and VII C shows turbine efficiencies based on shaft power (calculated from measured output power + rectifier and generator losses + parasitic losses + bearing and rotor windage losses) and enthalpy (based on measured turbine inlet temperature and pressure). These range from 27.6 to 59.6% with the lower efficiencies occurring at higher than design turbine back pressure.

Figure 711.10 is a recording of Run 030 from which the slope of the accelerating and deceleracing portions of turbine speed trace was used to determine shaft power and predicted turbine efficiency. This data is summarized in Table VII-D from which the following is evident:

Measured in and predicted in CP 25 agree

Calculated shaft loss and that based on output power generally agree

Calculated in based on acceleration/deceleration analysis agrees with the average in calculated from output power considering that flow to the turbine is cycling from 5 to 2 nozzles to maintain turbine speed at 55.1 Krpm. Thus the turbine appears to be operating close to predicted though the speed trace scale makes qualit - analysis difficult.

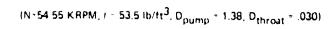
Turbine efficiency depends upon inlet conditions, exit conditions and degree of admission. As shown in Table VII D, the partial admission effect is significant (2 noz vs. 5 noz nt).

A further analysis was performed to determine if heat loss in the nozzle housing was contributing to low power output. Figure VII-11 is a sketch illustrating possible heat flow paths. The following data points were selected Pecause they represent a wide range of turbine inlet and outlet conditions.

Conditions

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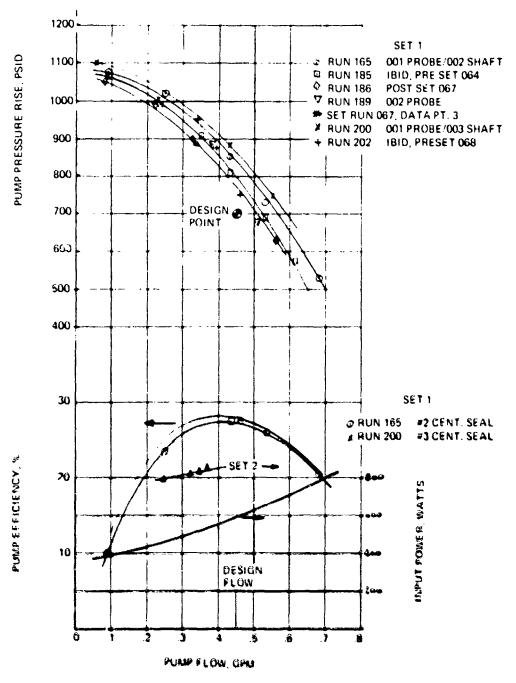


Figure VII-9 Page Pump Output & Performance Characteristic

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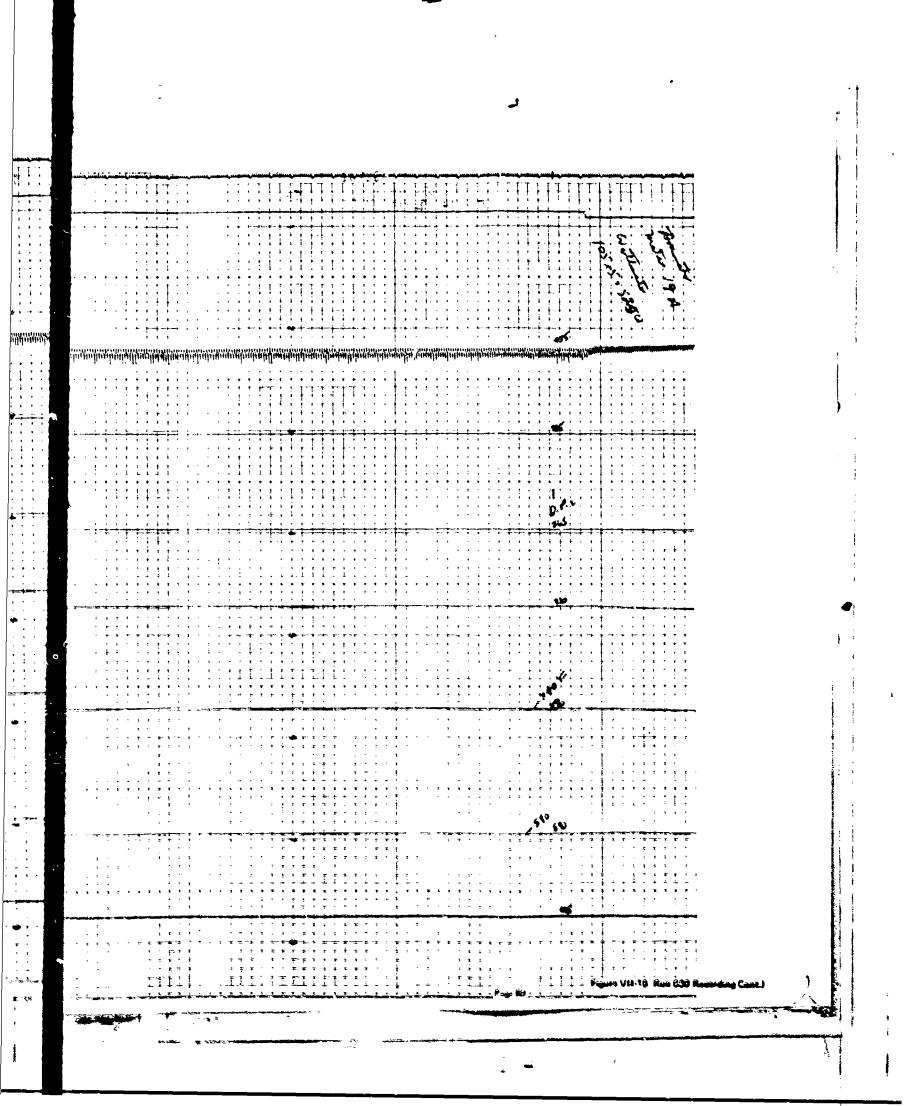
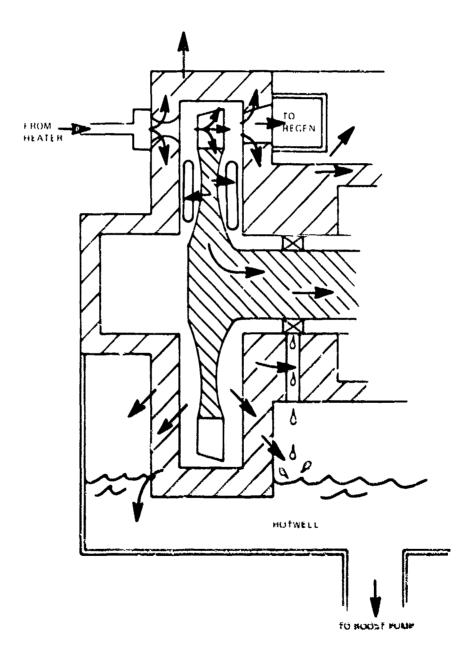


Table VII D. Turbina Performance

Data Point _	030 DP1	030 DP2	029 DP1	029 DP2	028 DP1	028 DP2
		775.5.5	250 July 1	*F.I.,*L=P	***	<u> </u>
TNI	840	840	830	774	812	812
(I) Accel	1.72	1 358	1 661	.455	1.137	943
(I) Decel	94	1 137	1.115	1.316	1 2	1 13
A+ID	2.66	2.495	2.776	1.771	2.337	2.074
Pin (5)	994	924	954	904	384	864
Pin (2)	959	944	1004	874	904	884
m (5) (£19)	.0342	.0318	.03276	.03194	03076	03007
m (2) (E19)	.0147	.01443	.01541	.01372	01397	01367
(m) av (E19)	0244	0231	.0242	.02283	.0224	0219
(m) meas.	.0284	0292				0363
Sheft loss w	1558	1680	2010	1301	1700	1496
Shaft loss (*) w	1600	1515	1700	1819	1864	1863
Реж рыа	3.6	5.0	2 7	49	31	38
HP _(S) meas.	3.60	3.44	4.15	2.14	3.25	2 82
HP ₍₅₎ E19			3.53	2 93	3 1 7	3 03
HP ₍₂₎ meas				676	1 25	1 03
HP(2) E19			1 30	877	1 12	1 03
ų t (5) ž 19						581
n t (2) €19	44	.423	45	404	445	435
Avg Pred (*)		49	.385	455	479	50

NOTES

- (*) From Table 7.2
- (5) Indicate 5 nozzles ætive
- (2) Indicate 2 nozzles active
- (£19) is computer performance program designation



France VII 11 Turbure Mant Flore Martin

028.2 Hotwell liquid level contacting turbine housing Design point turbine outlet conditions

16.5 Hotwell liquid level * 0, flow through into modified

& hotwell (holding tank attached to bottom of hotwe it

16-7 Design point turbine inlet condition

The objective of the analysis was to determine turbine efficiency usin:—st data and considering heat losses, to determine why the regenerator vapor inlet temperature is 30 · 60°F lower than it should be and why the different hotwell liquid levels did not ma. This is a significant change in output power. It is worth noting that Set 2 has produced up to 477 ratts net output power, but for all the tests on the everage, net output power is close to zero.

Three heat transfer analyses were conducted, the wet, partially dry, and dry cases to simulate the following conditions respectively. (1) hotwell liquid level contacting the nozzle plate, (2) hotwell liquid level below the nozzle plate with the bearing drainage flowing down the face of the plate and (3) no liquid in the hotwell with the bearing drainage not contacting the face of the plate. Note that lab experiments imply the bearing drainage flows down the face of the plate. Table VII E is a summary of this analysis for Run 030.1 which indicates that the wet case has approximately twice the heat loss as the dry case, and the predominant loss is the heat flow to the wheel. Table VII F uses these heat flows and applies them to the various tests to determine which case best represents each test, how the predicted regenerator vapor inlet temperature (TRVI) compares to that measured and what the real turbine efficiency is factoring in heat losses. The asterisks in Table VII F indicate the cases which typify each test run by choosing the case that most clearly matches measured TAVI. For example, the partially dry case best describes Run 030.1 since the calculated TRV' is only 120F lower than that measured. The heat loss at the inlet of the turbine is small but is a factor The corresponding turbine efficiencies compare well with the data of Tables VII B, C, and D. The turbine efficiency of Run 016 is low due to the very high back pressure. As the design point is approached, the turbine efficiency becomes higher and approaches that of Run 030 f

From this, a prediction is made of the expected output power with the correct design turbine conditions and what may be expected if the performance of certain components is improved. For this analyses, it is assumed that design point conditions are achieved at the inlet and exit of the turbine (by reducing non-condensible leaks into the low pressure side of the system) and that heat losses can be reduced to the dry case. Additionally, the generator and rectifier losses are taken as the worst possible case (would be lower using TRW data, reference Figure VII.12) and parasitics are taken as the highest measured (range ~ 466~605 watts). It is further assumed that the reduction in heat loss in the wheel only improves shaft gower indirectly through greater regeneration and the ability of the system to suggest greater mass flow.

Thus, the recults of this analysis, presented in Table VIIIG, are conservative and imply the following

With a $$8 \, \eta t$, 650 watto is the maximum power that can be expected out of $$at 2 \, a$, design point conditions.

The effect of heat less is not significant

The pitot pump is the greatest contributor to low output power

Table VII-E Heat Loss Summary (Run 030-1

		Partially	
	Wet	Dry	Dry
Inlet Gas → Inlet Hsg. (Q in)	509	398	342
Exh. Gas → Exh. Hsg. (Q _L exh)	119	71	38
Hot Gas → Wheel (Q _L)	2397	1158	308
Disc Friction (Df)	670	670	670
Pumping (P)	125	125	125
Total Loss from Exhaust	3820 B/hr	2422 B/hr	1484 S/nr

Run 030 conditions

m ~ 77.3 lb/hr

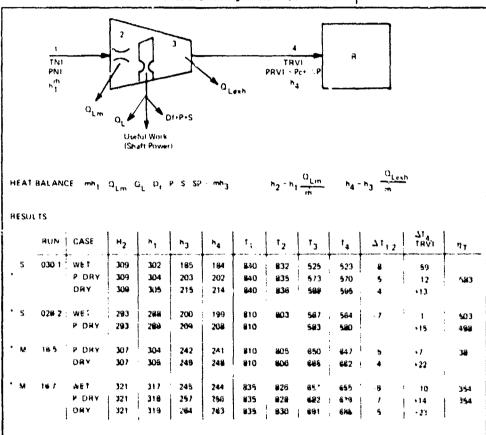
TNI - 8400F

PN1 = 974 psia

Pc = 3.6 - 4.0 psia

Scavenging Loss(s) - 410 B/hr

Table VII-F Effect of Heat Loss on Performance (Prediction of Regenerator Vapor Tin and $|\eta\rangle_{T})$



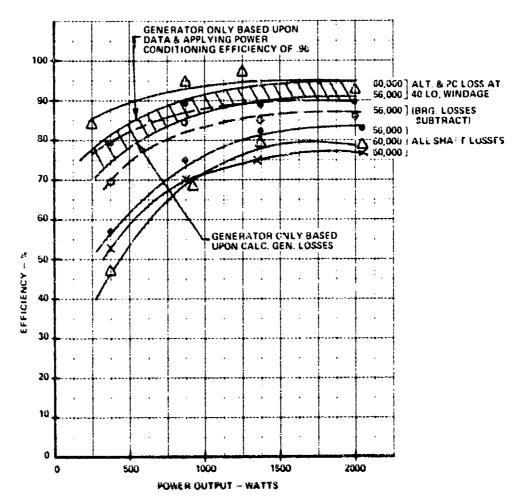


Figure VII-12 Alternator and Power Conditioning System Efficiency

Table VII-G Predicted Performance

		il Adm, losses Dlb/hr & ηt -	& partial fire (58	ate		
			120 lb/hr ηt = 58	E _R 85 ηυρ - 35	*n# - 8	8
	Shaft	Power, w	2470	3017	3179	
		Pump	900 1570	496 2521	496 2683	
		(B+W)	65 1505	65 2453	65 2618	
		GAR	286 (.81) 1219	422 (83) 2034	450 (.8 2168	3)
	Pa	rasitics	600 619 w	600 1434 w	600 1568 w	
	SUMMA	RY		Kilowatti	output	
				,	•	Ht. Loss
Run	Comments	η _t .58	Ht Loss	Ht Loss	Ht. Loss 'E _R 'pp	* ^Е Я • рр • трН
030-1	Partial Adm & fire rate 120 th hi & fft - 58	62			1 43	1.57
	Partial Adm - Low fit	.58	61	.58	1.21	1.32
028 2						
028 2 16-5	High back press	.68		83	1 36	1 47

Reducing the heat loss and increasing the performance of the regenerator, pitot pump and heater will bring output power to 1.2 ± 1.6 KW at a $10.4\pm13.9\%$ thermal efficiency.

Higher output power may be obtained by more fuel through-put.

SECTION VIII

VIII. IMPROVEMENTS

STARTUP

Automatic startup was not achieved on Set 2. This was due to two factors:

- Too high a degree of flow from the start pump which precluded enough temperature rise in the fluid prior to pitot pump takeover.
- Possible takeover by the pitot pump at too low a turbine speed and/or at too low a working fluid temperature.

These conditions caused the system to reach a bootstrap equilibrium point at a temperature below the critical point, at a flow above the design point and at a speed below rated.

The start pump is oversized and needs to have its output reduced to effect a bootstrap start that is compatible with the fluid heat input and turbine/pitot pump dynamics.

OUTPUT POWER AND EFFICIENCY

As the discussion in Section VII indicates, these factors relate to several components.

TURBINE: The turbine appears to be operating close to design though low by several points. Increasing the lap ratio would allow more optimum entry of the gases into the blade passage. Design point efficiency of this same turbine with a higher lap ratio has been achieved on the Remcom program.

REGENERATOR. On Set 1 the regenerator showed better performance than on Set 2. The construction is that of a core slipped into a housing. The implication is that there may be a significant amount of side leakage around the core on the Set 2 regenerator that did not exist on Set 1. Tighter dimensional control, investigation of thermal fatigue/expansion characteristics and improved design quality should increase the effectiveness to the design value.

HEATER. The heater efficiency is also lower than that of Set 1 and a few percentage points lower than design. Fundamentally, a fin tube heater would be more reproducible than the present 8-8 design. The design point efficiency in a fin-tube design is achievable in the same volume and at reduced weight in the 8-8 type.

PARASITICS: The efficiency of the constant frequency motor reduced parasities by a net of 50 watts factoring in the increased power of the quieter constant frequency gearbox. Further reduction can be achieved particularly if a single variable speed motor is used to support all parasities rather than the present variable and constant speed motors each driving selected parasitic devices.

EFFICIENCY. In summarizing the efficiency that can be expected with another generation of hardware, from Section VII it is seen that improvements in heat loss control, pitot pump efficiency, regenerator effectiveness and heater efficiency will yield $1.2-1.8~{\rm KW}$ at 10.4-13.9% thermal efficiency. Further improvement may also be made by increasing turbine tap ratio and reducing parasitic losses.

PITOT PUMP. The original prediction of pitot pump performance was 35%, that obtained on Set

1 was 28% and for Set 2 was about 15–16%. Figure VIII 1 illustrates the differences between the Set 1 and Set 2 probes. The probe for Set 2 was constructed in such a way as to be less expensive to fabricate. In so doing, several characteristics, such as the leading edge, X sectional symmetry, and inlet geometry of the nose changed. The housing cavity is also different. It is hypothesized that probe drag, recirculation and/or sidewall effects of the housing are inducing excessive losses.

An investigation was made to determine if the theoretical probe drag losses are consistent with achieving the original efficiency predictions which were obtained using scaling criteria. Table VIII A is a summary of measured power, predicted power and drag losses as a function of drag coefficient. Literature for streamline struts and foils indicate a $C_D \simeq .009$ is common which results in a power loss of 63 w. Adding extra drag for the nose ($C_D \simeq .1$ considering as a scoop) increases the power loss to 188 w including the centrifugal seal loss. This does not include recirculation, sidewall effects and internal inlet drag and is less than a 35% pump would permit (a total power of 215 w). However, the proximity of sidewalls can push C_D to .1 and in this case drag \approx 680 w which is comparable to that measured on Set 2.

This discussion indicates that there are geometric explanations for the higher Set 2 pitot pump power loss. To reduce the losses to that originally predicted is realistic but will require experimentation with the variables to arrive at the desired pump efficiency.

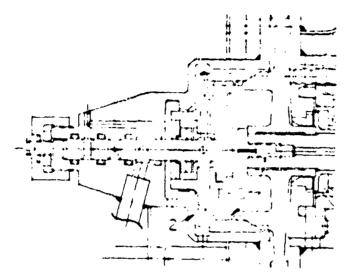
NOISE—While significant improvement was made in gearbox emitted noise, the CRU is still the major noise producer. Although between Set 1 and Set 2 the noise level was reduced (stiffening the hotwell); it is not sufficiently low to meet the noiseless 100 meter requirement. The reason is largely due to all the resonances of the hotwell not being eliminated. Thus, the hotwell responds to the rotational disturbance of the turbine assembly. Further improvement could be made by reducing the input disturbance. This would require improving the balance of the rotating assembly by balancing in the operating speed region. Sundstrand's Remoon power plant is an example of a very quiet machine. It is heavy but nonetheless attests to the solution approach of stiffening the hotwell as the method to preclude responding to the one-per rev of the turbine rotating assembly Minimal weight increase would be incurred by using ribs, better mount arrangement, elimination of flats on the hotwell which easily deflect, and a non-cantilevered mounted turbine rotating assembly to eliminate its nwn self-induced vibration.

BOOST PUMP. Between Set 1 and Set 2 an improved phost pump was developed, however, there are circumstances where boiling occurs as the condenser overcools the condensate during transient periods. Even the Set 2 boost pump will cavitate in these circumstances. Sundstrand has developed for Remcom a boost pump capable of handling boiling CP 2S. This is a nominal 10,000 rpm centrifugal pump which has to date exceeded 6000 hours of operation and demonstrated its integrity. This pump is ideally suited to the MERDC 1.5 KW unit since it is designed for comparable flows and pressures.

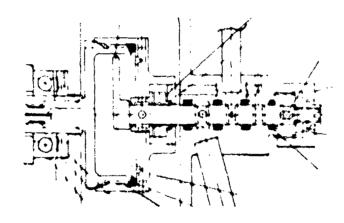
OTHER Other areas of improvement were presented in the Set 1 Final Report, ATR 1182, dated 6.24.74. Many of these were not incorporated into Set 2 and remain valid.

CONTROLS: The controllers used for Units 1 and 2 were designed to meet the requirements of the specification including use of preferred parts. To meet the circuit requirements over the specified temperature range and environmental conditions, it is not necessary to use the preferred parts of the specification.

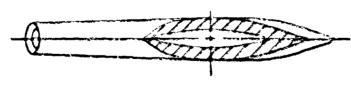
The following discussion of a simplified controller centers on circuits that were chosen to reduce



MERDC UNIT 1 EP 2559 1001



MERDC UNIT 2 EP 2559 5969



MERDO EP2559-1148 HAND FINISHED & POLISHED WITH ROUND LEADING EDGE t= 070 ± 001 e= 285 ± 008

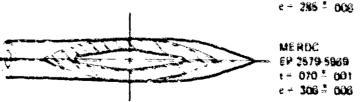


Figure VIII 1 for 1 and Set 2 Protes

Pair 10

	MERDC EP2559
	1148 5969
	(UNIT 1) (U:-1T 2)
MEASURED EFFICIENCY (%)	28 15.6
Power (w)	470 840
Hyd. work (w)	130 130
P Hyd, wk (w)	340 710
Cent. Seal Est. (w)	32 32
Drag + Recirc. Losses (w)	308 678
PREDICTED EFFICIENCY (%)	35
Power (w)	377° @ 4 SYS - 10%
Hyd work (w)	130
P Hyd. wk (w)	247
Cent Seal Est. (w)	32
Drag + Recire, Losses (w)	215
PROBE PREDICTIONS	
Vel Range (ft/sec)	60 300
N _R Range	$2.6 \times 10^{5} - 9.2 \times 10^{6}$
Cent. Sear Loss (w)	32 32
Drag @ C _D = 009 (w)	63
@ C _D − .060 (w)	4:0
© CD - 100 (w)	680
@ CD - 009 + 03 N	lose (w) 100
@ CO - 009 + 1 No	188 (w)

the overall parts count and meet the operational requirements. They are suggested circuits and have not been built and tested. In addition, they do not always use the military preferred parts list since this list lags the state of the art and, therefore, its use may induce less than ideal design.

The controller block diagram is shown in Figure VIII 2.

The auxiliary requiator can use a precision I,C regulator instead of zener diode and op amps. The output stage can remain the same. The triangle generator output could be shared by both the auxiliary and main regulators.

The main alternator regulator uses an 1.C, regulator for error amplification and reference voltage source. A comparator sums the output of the regulator and a ramp generator to produce a PWM signal to drive the field. The field driver circuit can remain the same.

The current limit circuit uses an F.E.T. as a variable resistance to lower the reference voltage coming from the voltage adjust pot. The current limit approximates a constant power slope.

The new regulator circuit as shown in Figures VIII 3 and VIII-4 has 35 parts compared to the previous design of 68 parts.

The proposed temperature regulator circuit uses the same block diagram approach to the control loop as the existing circuit. If deviation from the preferred parts list is allowed, Cmos and optical isolators can be used, simplifying the VCO and one shot circuitry (Figure VIII 5). The input amplifier will remain the same, an I.C. instrument amplifier. The transistor output stage can be simplified if Darlington transistors are used.

Three approaches to the control loop can be taken. A bang-bang loop would be the fastest and simplest circuit. Response to temperature changes would be immediate and high accuracy can be achieved. A bang-bang-loop may cause thermal stressing of the fluid.

A second method which does not gause thermal stressing is a linear proportional loop. In order to make this loop stable, long time constants would be required which would also make it a slow loop. During load application, temperature undershoot would occur and during load removal, overshoot would occur.

A third method would use a limear proportional loop with load compensation. Afternator load would be sensed, and load change would be inserted into the heater loop to speed up the response

Of the above methods, the first one would save the most parts and the third one the least. The first method would save 30 parts, the second approximately 20 parts and the third approximately 15 parts. Analysis and experimentation would be necessary to identify the optimum trade off.

With Cross circuitry used extensively in this design, the +5 volt power supply will not be needed. The +15 and -15 v could be provided by pre-packaged power supplies. The present design uses 42 parts for the three power supplies. This would be replaced by two power supply modules.

The battery charger will remain the same. The way it is attached to the battery is shown in Figure VIII 6.

Due to the present method of starting the turbine, the controller does not need any sixturnising of

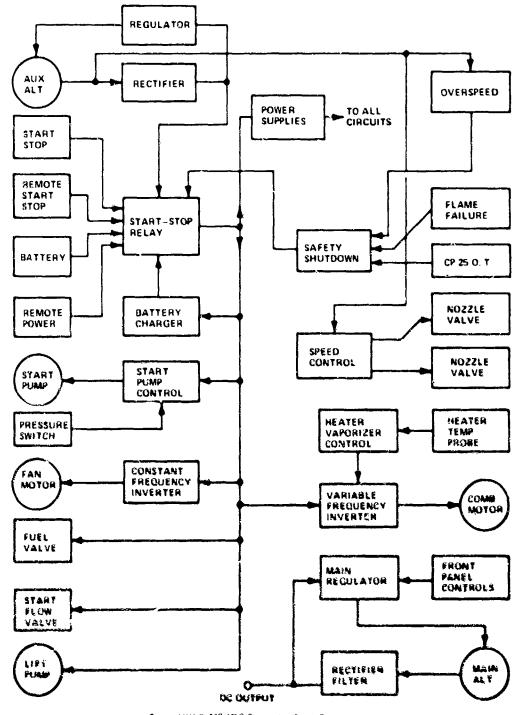
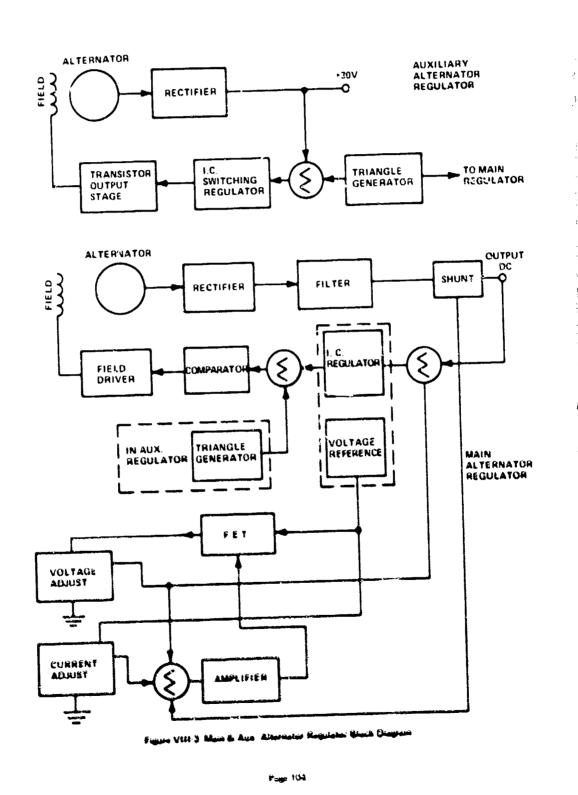


Figure VIII-2 MERDC Controller Black Diegraff



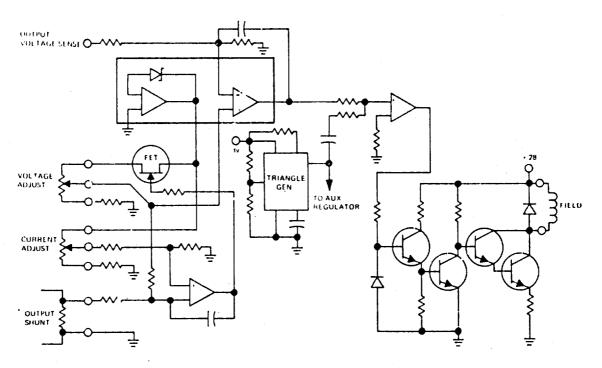


Figure VIII-4 Preliminary Schematic Main Alternator Regulator

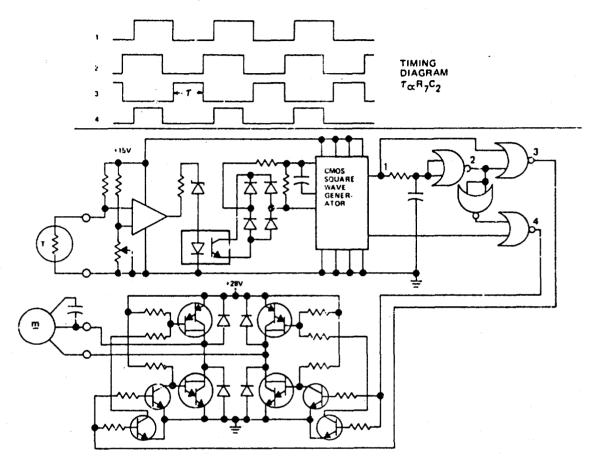


Figure VIII-5 Prelim. Schematic Temp. Reg. Circuit

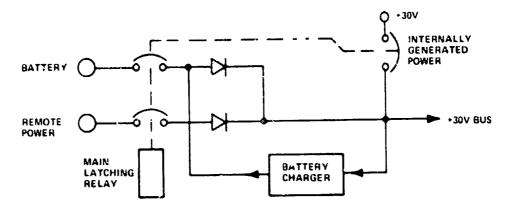


Figure VIII-6 Battery Charge Block Diagram

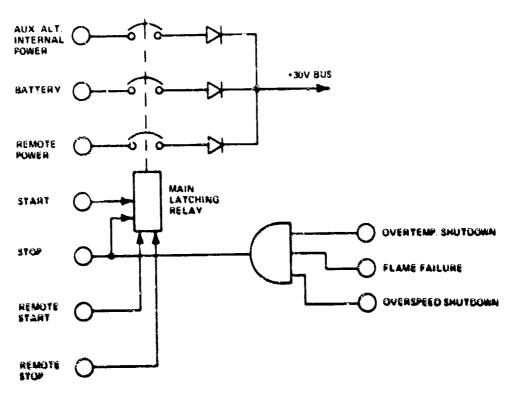


Figure VIII-7 Start - Step Lagis Diagram

time delays. One main latching circuit can control all power coming into the controller. This would consist of two power relays that have contact ratings compatible with the start pump and fan motor current requirements. The logic diagram is shown in Figure VIII 7.

The speed control and overspeed safety circuit will remain the same except that Cmos will replace the TTU logic.

The constant frequency inverter can remain a packaged purchased inverter or incorporated into the controls depending upon the cost trade-off,

The start pump control circuit which allows for starting the pump motor will remain the same.

The main alternator rectifier filter circuit will also remain the same as the current Unit 2 controller,

REPACKAGING CONCEPT

The existing $2' \times 2' \times 2'$ package can be developed into a viable highly efficient power supply, however it is not the optimum package. Evidence from development data to date includes.

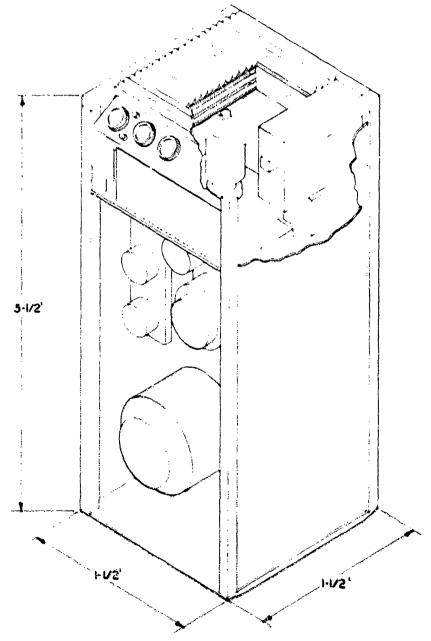
Noise emitted by condenser fan.

May not need both constant and variable frequency mechanical circuits. In fact, it is desirable to have condenser coolant fan speed follow working fluin flow rather than run at constant speed.

For increased operating margin, the boost pump should have more liquid head

The burner operates better extended away from the heater rather than buried

A repackaged unit would be 3.5° \times 1.5° \times 1.5° and is shown conceptually in Figure VIII 8. There is no volume or weight increase (currently 8 ft³ and 210 pounds). Further development of a bootstrap start, simplified controls and simplified accessory drive should reduce the parts count, weight, and cost. The repackaging effort will reduce noise and improve mechanical operation.



ES98-A

Figure VIII & 1.5KW ORC Copachaged Contage

Page 109

SECTION IX

CALIBRATION REQUIREMENTS SUMMARY

IX. CALIBRATION REQUIREMENTS SUMMARY

The calibration requirements summary establishes for the measured parameters the traceability of measurement from the operational equipment to the standards of the National Bureau of Standards.

Table 1X A lists the parameters measured for which traceability is provided with the following records. Table 1X B defineates thermocouple calibration.

Page 110

Table IX-A Traceability and Record Identification

Parameter	Description	ID Number
TNI	Temperature nozzle inlet	0775100K
TRO	Temperature regenerator liquid out	0779074K
TRVI	Temperature regenerator vapor inlet	0775 06 2K
THWL	Temperature hotwell liquid	077 509 9K
TVO	Temperature vaporizer out	0775103K
THE	Temperature heater exhaust	0775078K
TRVO	Temperature regenerator vapor out	0775087K
TRI	Temperature regenerator liquid inlet	0775085K
QE	Flow economizer	FL 205
QR	Flow regenerator	FL 308
QBP	Flow boost pump	FL 277
PNI	Pressure nozzle inlet	PT 204 & PT 160*
PC	Pressure condenser	PT 744 & PT 423
PBO	Pressure boost pump out	PT 232 & PT 760
bB _t	Pressure bearing inlet	PT 186
* Used onl	y during N ₂ spin checks (PVO)	
NOTE.	The standard quality control period betw	een calibrations is.
	26 weeks for pressure transducers from use after calibration	i the time of initial
	26 weeks for flowmeters from the time calibration	e of imitial use after
	52 weeks for thermocouples from the calibration	time of initial use after

Table 1X-8 Thermocouple Calibration

Range: 0°F to 2400°F

Calibration date: Month 7, Year 1974

Usable period after calibration: 1 year

Instrument calibration: Model 1.8 x 12 K

Calibration points: 32.0 + 5.0°F

786.4 + 5.9°F 1761.4 + 13.2°F Type -- K

Type thermocouple. Chromel - Alumel

FEGUTETER S/N: F. 1872 S/1:: 4747 Harrison Ave. Rockford, Illimort 61101 Pinnae (815) 226-6000 9

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CALIFRATION DATA John Fluke Digital Hultimeter Hodel 8375A

Identification VE-150	
Date Calibrated 01-15-25 By 6:11	
Calibration Not Valid After Sold (1994)	
Standards Used 14-4/1 1-5: 1-31,32 33 34	35,41
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NOTE: The following calibration steps are to be performed only if the above checks were found out of Specs.

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- 6. Bias Current Adjustment.
- 7. Reference Voitage Adjustment.
- 8. A-D Zero Adjustment.
- 9. + Cal. Adjustment.
- 10. Ladder Cal.
- 11. Negative Cal. Adjustment.
- 12. Remainder Adjustment.
- 13. Comparator Lavel Adjustment.
- 14. RMS Range Amplifier Zero.
- 15. Balance Amplifier Zero.
- 16. Balance Gain,
- 17. AC Zero.
- 18. Calibration Adjustment/Check.
- 19. Coarse Calibration.
- 20. Buffer DC Calibration.
- 21. Active Filter.
- 22. Kilohms Calibration,
- 23. Ohms Calibration.

Security Classification	INT CONTROL DATA	PAD	هي والكنود الدراية المراوي والأفاد				
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